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**INVARIANT DIFFERENTIAL OPERATORS ON THE  
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## INVARIANT DIFFERENTIAL OPERATORS ON THE MINKOWSKI-EUCLID SPACE

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ABSTRACT. For two positive integers  $m$  and  $n$ , let  $\mathcal{P}_n$  be the open convex cone in  $\mathbb{R}^{n(n+1)/2}$  consisting of positive definite  $n \times n$  real symmetric matrices and let  $\mathbb{R}^{(m,n)}$  be the set of all  $m \times n$  real matrices. In this paper, we investigate differential operators on the non-reductive homogeneous space  $\mathcal{P}_n \times \mathbb{R}^{(m,n)}$  that are invariant under the natural action of the semidirect product group  $GL(n, \mathbb{R}) \ltimes \mathbb{R}^{(m,n)}$  on the Minkowski-Euclid space  $\mathcal{P}_n \times \mathbb{R}^{(m,n)}$ . These invariant differential operators play an important role in the theory of automorphic forms on  $GL(n, \mathbb{R}) \ltimes \mathbb{R}^{(m,n)}$  generalizing that of automorphic forms on  $GL(n, \mathbb{R})$ .

### 1. Introduction

Let

$$\mathcal{P}_n = \left\{ Y \in \mathbb{R}^{(n,n)} \mid Y = {}^t Y > 0 \right\}$$

be the open convex cone of positive definite symmetric real matrices of degree  $n$  in the Euclidean space  $\mathbb{R}^{n(n+1)/2}$ , where  $F^{(k,l)}$  denotes the set of all  $k \times l$  matrices with entries in a commutative ring  $F$  for two positive integers  $k$  and  $l$  and  ${}^t M$  denotes the transpose matrix of a matrix  $M$ . Then the general linear group  $GL(n, \mathbb{R})$  acts on  $\mathcal{P}_n$  transitively by

$$(1.1) \quad g \cdot Y = gY {}^t g, \quad g \in GL(n, \mathbb{R}), \quad Y \in \mathcal{P}_n.$$

Therefore,  $\mathcal{P}_n$  is a symmetric space which is diffeomorphic to the quotient space  $GL(n, \mathbb{R})/O(n)$ , where  $O(n)$  denotes the orthogonal group of degree  $n$ . A. Selberg [10] investigated differential operators on  $\mathcal{P}_n$  invariant under the action (1.1) of  $GL(n, \mathbb{R})$  (cf. [7, 8]).

Let

$$GL_{n,m} = GL(n, \mathbb{R}) \ltimes \mathbb{R}^{(m,n)}$$

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be the semidirect product of  $GL(n, \mathbb{R})$  and the abelian additive group  $\mathbb{R}^{(m,n)}$  equipped with the following multiplication law

$$(g, \lambda) \cdot (h, \mu) = (gh, \lambda {}^t h^{-1} + \mu),$$

where  $g, h \in GL(n, \mathbb{R})$  and  $\lambda, \mu \in \mathbb{R}^{(m,n)}$ . Then we have the *natural action* of  $GL_{n,m}$  on the non-reductive homogeneous space  $\mathcal{P}_n \times \mathbb{R}^{(m,n)}$  given by

$$(1.2) \quad (g, \lambda) \cdot (Y, V) = (gY {}^t g, (V + \lambda) {}^t g),$$

where  $g \in GL(n, \mathbb{R})$ ,  $\lambda \in \mathbb{R}^{(m,n)}$ ,  $Y \in \mathcal{P}_n$  and  $V \in \mathbb{R}^{(m,n)}$ .

For brevity, we set  $\mathcal{P}_{n,m} = \mathcal{P}_n \times \mathbb{R}^{(m,n)}$  and  $K = O(n)$ . Since the action (1.2) of  $GL_{n,m}$  is transitive,  $\mathcal{P}_{n,m}$  is diffeomorphic to  $GL_{n,m}/K$ . We observe that the action (1.2) of  $GL_{n,m}$  generalizes the action (1.1) of  $GL(n, \mathbb{R})$ .

The significance in studying the non-reductive homogeneous space  $\mathcal{P}_{n,m}$  may be explained as follows. Let

$$\Gamma_{n,m} = GL(n, \mathbb{Z}) \times \mathbb{Z}^{(m,n)}$$

be the arithmetic subgroup of  $GL_{n,m}$ , where  $\mathbb{Z}$  is the ring of integers. The arithmetic quotient  $\Gamma_{n,m} \backslash \mathcal{P}_{n,m}$  may be regarded as the universal family of principally polarized real tori of dimension  $mn$  (cf. [14]). We propose to name the space  $\mathcal{P}_{n,m}$  the *Minkowski-Euclid space* since it was H. Minkowski [9] who found a fundamental domain for  $\mathcal{P}_n$  with respect to the arithmetic subgroup  $GL(n, \mathbb{Z})$  by means of the reduction theory. In this setting, using the invariant differential operators on  $\mathcal{P}_{n,m}$ , we can develop a theory of automorphic forms on  $\mathcal{P}_{n,m}$  generalizing that on  $\mathcal{P}_n$ .

The aim of this paper is to study differential operators on  $\mathcal{P}_{n,m}$  that are invariant under the action (1.2) of  $GL_{n,m}$ . This paper is organized as follows. In Section 2, we review differential operators on  $\mathcal{P}_n$  invariant under the action (1.1) of  $GL(n, \mathbb{R})$ . In Section 3, we investigate differential operators on  $\mathcal{P}_{n,m}$  invariant under the action (1.2) of  $GL_{n,m}$ . For two positive integers  $m$  and  $n$ , let

$$S_{n,m} = \left\{ (X, Z) \mid X = {}^t X \in \mathbb{R}^{(n,n)}, Z \in \mathbb{R}^{(m,n)} \right\}$$

be the real vector space of dimension  $\frac{n(n+1)}{2} + mn$ . From the adjoint action of the group  $GL_{n,m}$ , we have the *natural action* of the orthogonal group  $O(n)$  on  $S_{n,m}$  given by

$$(1.3) \quad k \cdot (X, Z) = (kX {}^t k, Z {}^t k), \quad k \in O(n), (X, Z) \in S_{n,m}.$$

The action (1.3) of  $K = O(n)$  induces canonically the representation  $\sigma$  of  $O(n)$  on the polynomial algebra  $\text{Pol}(S_{n,m})$  consisting of complex-valued polynomial functions on  $S_{n,m}$ . Let  $\text{Pol}(S_{n,m})^K$  denote the subalgebra of  $\text{Pol}(S_{n,m})$  consisting of all polynomials on  $S_{n,m}$  invariant under the representation  $\sigma$  of  $O(n)$ , and  $\mathbb{D}(\mathcal{P}_{n,m})$  denote the algebra of all differential operators on  $\mathcal{P}_{n,m}$  invariant under the action (1.2) of  $GL_{n,m}$ . We see that there is a canonically defined

linear bijection of  $\text{Pol}(S_{n,m})^K$  onto  $\mathbb{D}(\mathcal{P}_{n,m})$  which is not multiplicative. We will see that  $\mathbb{D}(\mathcal{P}_{n,m})$  is *not* commutative. The most important problem here is in finding a complete list of explicit generators of  $\text{Pol}(S_{n,m})^K$  and a complete list of explicit generators of  $\mathbb{D}(\mathcal{P}_{n,m})$ . We propose several natural problems. We present some explicit invariant differential operators which may be useful. In Section 4, we deal with the case when  $n = 1$ . In Section 5, we deal with the case when  $n = 2$  and  $m = 1, 2$ . In Section 6, we deal with the case when  $n = 3$  and  $m = 1, 2$ . In Section 7, we deal with the case when  $n = 4$  and  $m = 1, 2$ . In the final section, we present some open problems and discuss a notion of automorphic forms on  $\mathcal{P}_{n,m}$  using  $GL_{n,m}$ -invariant differential operators on the Minkowski-Euclid space  $\mathcal{P}_{n,m}$ .

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**Notations.** Denote by  $\mathbb{Q}$ ,  $\mathbb{R}$  and  $\mathbb{C}$  the field of rational numbers, the field of real numbers and the field of complex numbers, respectively. Denote by  $\mathbb{Z}$  and  $\mathbb{Z}^+$  the ring of integers and the set of all positive integers, respectively. The symbol “:=” means that the expression on the right is the definition of that on the left. For two positive integers  $k$  and  $l$ ,  $F^{(k,l)}$  denotes the set of all  $k \times l$  matrices with entries in a commutative ring  $F$ . For a square matrix  $A \in F^{(k,k)}$  of degree  $k$ ,  $\text{tr}(A)$  denotes the trace of  $A$ . For any  $M \in F^{(k,l)}$ ,  ${}^tM$  denotes the transposed matrix of  $M$ . For a positive integer  $n$ ,  $I_n$  denotes the identity matrix of degree  $n$ .

## 2. Review on invariant differential operators on $\mathcal{P}_n$

For a variable  $Y = (y_{ij}) \in \mathcal{P}_n$ , set

$$dY = (dy_{ij}) \quad \text{and} \quad \frac{\partial}{\partial Y} = \left( \frac{1 + \delta_{ij}}{2} \frac{\partial}{\partial y_{ij}} \right),$$

where  $\delta_{ij}$  denotes the Kronecker delta symbol.

For a fixed element  $g \in GL(n, \mathbb{R})$ , put

$$Y_* = g \cdot Y = gY {}^tg, \quad Y \in \mathcal{P}_n.$$

Then

$$(2.1) \quad dY_* = g dY {}^tg \quad \text{and} \quad \frac{\partial}{\partial Y_*} = {}^tg^{-1} \frac{\partial}{\partial Y} g^{-1}.$$

Consider the following differential operators

$$(2.2) \quad D_i = \text{tr} \left( \left( Y \frac{\partial}{\partial Y} \right)^i \right), \quad i = 1, 2, \dots, n,$$

where  $\text{tr}(A)$  denotes the trace of a square matrix  $A$ . By Formula (2.1), we get

$$\left(Y_* \frac{\partial}{\partial Y_*}\right)^i = g \left(Y \frac{\partial}{\partial Y}\right)^i g^{-1}$$

for any  $g \in GL(n, \mathbb{R})$ . Hence each  $D_i$  is invariant under the action (1.1) of  $GL(n, \mathbb{R})$ .

Selberg [10] proved the following.

**Theorem 2.1.** *The algebra  $\mathbb{D}(\mathcal{P}_n)$  of all differential operators on  $\mathcal{P}_n$  invariant under the action (1.1) of  $GL(n, \mathbb{R})$  is generated by  $D_1, D_2, \dots, D_n$ . Furthermore,  $D_1, D_2, \dots, D_n$  are algebraically independent and  $\mathbb{D}(\mathcal{P}_n)$  is isomorphic to the commutative ring  $\mathbb{C}[x_1, x_2, \dots, x_n]$  with  $n$  indeterminates  $x_1, x_2, \dots, x_n$ .*

*Proof.* The proof can be found in [4], p. 337, [8], pp. 64–66 and [11], pp. 29–30. The last statement follows immediately from the work of Harish-Chandra [1, 2] or [4], p. 294.  $\square$

Let  $\mathfrak{g} = \mathbb{R}^{(n,n)}$  be the Lie algebra of  $GL(n, \mathbb{R})$ . The adjoint representation  $\text{Ad}$  of  $GL(n, \mathbb{R})$  is given by

$$\text{Ad}(g) = gXg^{-1}, \quad g \in GL(n, \mathbb{R}), \quad X \in \mathfrak{g}.$$

The Killing form  $B$  of  $\mathfrak{g}$  is given by

$$B(X, Y) = 2n \text{tr}(XY) - 2 \text{tr}(X) \text{tr}(Y), \quad X, Y \in \mathfrak{g}.$$

Since  $B(aI_n, X) = 0$  for all  $a \in \mathbb{R}$  and  $X \in \mathfrak{g}$ ,  $B$  is degenerate. So the Lie algebra  $\mathfrak{g}$  of  $GL(n, \mathbb{R})$  is not semi-simple.

The Lie algebra  $\mathfrak{k}$  of  $K$  is

$$\mathfrak{k} = \{ X \in \mathfrak{g} \mid X + {}^tX = 0 \}.$$

Let  $\mathfrak{p}$  be the subspace of  $\mathfrak{g}$  defined by

$$\mathfrak{p} = \left\{ X \in \mathfrak{g} \mid X = {}^tX \in \mathbb{R}^{(n,n)} \right\}.$$

Then

$$\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$$

is the direct sum of  $\mathfrak{k}$  and  $\mathfrak{p}$  with respect to the Killing form  $B$ . Since  $\text{Ad}(k)\mathfrak{p} \subset \mathfrak{p}$  for any  $k \in K$ ,  $K$  acts on  $\mathfrak{p}$  via the adjoint representation by

$$(2.3) \quad k \cdot X = \text{Ad}(k)X = kX {}^tk, \quad k \in K, \quad X \in \mathfrak{p}.$$

The action (2.3) induces the action of  $K$  on the polynomial algebra  $\text{Pol}(\mathfrak{p})$  of  $\mathfrak{p}$  and the symmetric algebra  $S(\mathfrak{p})$ . Denote by  $\text{Pol}(\mathfrak{p})^K$  (resp.,  $S(\mathfrak{p})^K$ ) the subalgebra of  $\text{Pol}(\mathfrak{p})$  (resp.,  $S(\mathfrak{p})$ ) consisting of all  $K$ -invariants. The following inner product  $(\ , \ )$  on  $\mathfrak{p}$  defined by

$$(X, Y) = B(X, Y), \quad X, Y \in \mathfrak{p}$$

gives an isomorphism as vector spaces

$$(2.4) \quad \mathfrak{p} \cong \mathfrak{p}^*, \quad X \mapsto f_X, \quad X \in \mathfrak{p},$$

where  $\mathfrak{p}^*$  denotes the dual space of  $\mathfrak{p}$  and  $f_X$  is the linear functional on  $\mathfrak{p}$  defined by

$$f_X(Y) = (Y, X), \quad Y \in \mathfrak{p}.$$

It is known that there is a canonical linear bijection of  $S(\mathfrak{p})^K$  onto  $\mathbb{D}(\mathcal{P}_n)$ . Identifying  $\mathfrak{p}$  with  $\mathfrak{p}^*$  by the above isomorphism (2.4), we get a canonical linear bijection

$$(2.5) \quad \Theta_n : \text{Pol}(\mathfrak{p})^K \longrightarrow \mathbb{D}(\mathcal{P}_n)$$

of  $\text{Pol}(\mathfrak{p})^K$  onto  $\mathbb{D}(\mathcal{P}_n)$ . The map  $\Theta_n$  is described explicitly as follows. Put  $N = n(n+1)/2$ . Let  $\{\xi_\alpha \mid 1 \leq \alpha \leq N\}$  be a basis of  $\mathfrak{p}$ . If  $P \in \text{Pol}(\mathfrak{p})^K$ , then

$$(2.6) \quad (\Theta_n(P)f)(gK) = \left[ P \left( \frac{\partial}{\partial t_\alpha} \right) f \left( g \exp \left( \sum_{\alpha=1}^N t_\alpha \xi_\alpha \right) K \right) \right]_{(t_\alpha)=0},$$

where  $f \in C^\infty(\mathcal{P}_n)$ . We refer the reader to [3, 4] for more detail. In general, it is difficult to express  $\Theta_n(P)$  explicitly for a polynomial  $P \in \text{Pol}(\mathfrak{p})^K$ .

Let

$$(2.7) \quad q_i(X) = \text{tr}(X^i), \quad i = 1, 2, \dots, n$$

be the polynomials on  $\mathfrak{p}$ . Here we take coordinates  $x_{11}, x_{12}, \dots, x_{nn}$  in  $\mathfrak{p}$  given by

$$X = \begin{pmatrix} x_{11} & \frac{1}{2}x_{12} & \dots & \frac{1}{2}x_{1n} \\ \frac{1}{2}x_{12} & x_{22} & \dots & \frac{1}{2}x_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{1}{2}x_{1n} & \frac{1}{2}x_{2n} & \dots & x_{nn} \end{pmatrix}.$$

For any  $k \in K$ ,

$$(k \cdot q_i)(X) = q_i(k^{-1}Xk) = \text{tr}(k^{-1}X^ik) = q_i(X), \quad i = 1, 2, \dots, n.$$

Thus  $q_i \in \text{Pol}(\mathfrak{p})^K$  for  $i = 1, 2, \dots, n$ . By a classical invariant theory (cf. [5, 12]), we can prove that the algebra  $\text{Pol}(\mathfrak{p})^K$  is generated by the polynomials  $q_1, q_2, \dots, q_n$  and that  $q_1, q_2, \dots, q_n$  are algebraically independent. Using Formula (2.6), we can show without difficulty that

$$\Theta_n(q_1) = \text{tr} \left( 2Y \frac{\partial}{\partial Y} \right).$$

However,  $\Theta_n(q_i)$  ( $i = 2, 3, \dots, n$ ) are yet known explicitly.

We propose the following conjecture.

**Conjecture 1.** For any  $n$ ,

$$\Theta_n(q_i) = \text{tr} \left( \left( 2Y \frac{\partial}{\partial Y} \right)^i \right), \quad i = 1, 2, \dots, n.$$

*Remark.* The author has verified that the above conjecture is true for  $n = 1, 2$ .

For a positive real number  $A$ ,

$$ds_{n;A}^2 = A \cdot \text{tr}(Y^{-1} dY Y^{-1} dY)$$

is a Riemannian metric on  $\mathcal{P}_n$  invariant under the action (1.1). The Laplacian  $\Delta_{n;A}$  of  $ds_{n;A}^2$  is given by

$$\Delta_{n;A} = \frac{1}{A} \text{tr} \left( \left( Y \frac{\partial}{\partial Y} \right)^2 \right).$$

For instance, consider the case when  $n = 2$  and  $A > 0$ . If we write for  $Y \in \mathcal{P}_2$ ,

$$Y = \begin{pmatrix} y_1 & y_3 \\ y_3 & y_2 \end{pmatrix} \quad \text{and} \quad \frac{\partial}{\partial Y} = \begin{pmatrix} \frac{\partial}{\partial y_1} & \frac{1}{2} \frac{\partial}{\partial y_3} \\ \frac{1}{2} \frac{\partial}{\partial y_3} & \frac{\partial}{\partial y_2} \end{pmatrix},$$

then

$$\begin{aligned} ds_{2;A}^2 &= A \text{tr}(Y^{-1} dY Y^{-1} dY) \\ &= \frac{A}{(y_1 y_2 - y_3^2)^2} \left\{ y_2^2 dy_1^2 + y_1^2 dy_2^2 + 2(y_1 y_2 + y_3^2) dy_1 dy_2 \right. \\ &\quad \left. + 2y_3^2 dy_1 dy_2 - 4y_2 y_3 dy_1 dy_3 - 4y_1 y_3 dy_2 dy_3 \right\} \end{aligned}$$

and its Laplacian  $\Delta_{2;A}$  on  $\mathcal{P}_2$  is

$$\begin{aligned} \Delta_{2;A} &= \frac{1}{A} \text{tr} \left( \left( Y \frac{\partial}{\partial Y} \right)^2 \right) \\ &= \frac{1}{A} \left\{ y_1^2 \frac{\partial^2}{\partial y_1^2} + y_2^2 \frac{\partial^2}{\partial y_2^2} + \frac{1}{2}(y_1 y_2 + y_3^2) \frac{\partial^2}{\partial y_3^2} \right. \\ &\quad \left. + 2 \left( y_3^2 \frac{\partial^2}{\partial y_1 \partial y_2} + y_1 y_3 \frac{\partial^2}{\partial y_1 \partial y_3} + y_2 y_3 \frac{\partial^2}{\partial y_2 \partial y_3} \right) \right. \\ &\quad \left. + \frac{3}{2} \left( y_1 \frac{\partial}{\partial y_1} + y_2 \frac{\partial}{\partial y_2} + y_3 \frac{\partial}{\partial y_3} \right) \right\}. \end{aligned}$$

### 3. Invariant differential operators on $\mathcal{P}_{n,m}$

For a variable  $(Y, V) \in \mathcal{P}_{n,m}$  with  $Y \in \mathcal{P}_n$  and  $V \in \mathbb{R}^{(m,n)}$ , put

$$Y = (y_{ij}) \text{ with } y_{ij} = y_{ji}, \quad V = (v_{kl}),$$

$$dY = (dy_{ij}), \quad dV = (dv_{kl}),$$

$$[dY] = \wedge_{i \leq j} dy_{ij}, \quad [dV] = \wedge_{k,l} dv_{kl},$$

and

$$\frac{\partial}{\partial Y} = \left( \frac{1 + \delta_{ij}}{2} \frac{\partial}{\partial y_{ij}} \right), \quad \frac{\partial}{\partial V} = \left( \frac{\partial}{\partial v_{kl}} \right),$$

where  $1 \leq i, j, l \leq n$  and  $1 \leq k \leq m$ .

For a fixed element  $(g, \lambda) \in GL_{n,m}$ , write

$$(Y_*, V_*) = (g, \lambda) \cdot (Y, V) = (g Y {}^t g, (V + \lambda) {}^t g),$$

where  $(Y, V) \in \mathcal{P}_{n,m}$ . Then we get

$$(3.1) \quad Y_* = g Y {}^t g, \quad V_* = (V + \lambda) {}^t g$$

and

$$(3.2) \quad \frac{\partial}{\partial Y_*} = {}^t g^{-1} \frac{\partial}{\partial Y} g^{-1}, \quad \frac{\partial}{\partial V_*} = \frac{\partial}{\partial V} g^{-1}.$$

**Lemma 3.1.** For any two positive real numbers  $A$  and  $B$ , the following metric  $ds_{n,m;A,B}^2$  on  $\mathcal{P}_{n,m}$  defined by

$$(3.3) \quad ds_{n,m;A,B}^2 = A \sigma(Y^{-1} dY Y^{-1} dY) + B \sigma(Y^{-1} {}^t (dV) dV)$$

is a Riemannian metric on  $\mathcal{P}_{n,m}$  which is invariant under the action (1.2) of  $GL_{n,m}$ . The Laplacian  $\Delta_{n,m;A,B}$  of  $(\mathcal{P}_{n,m}, ds_{n,m;A,B}^2)$  is given by

$$\Delta_{n,m;A,B} = \frac{1}{A} \sigma \left( \left( Y \frac{\partial}{\partial Y} \right)^2 \right) - \frac{m}{2A} \sigma \left( Y \frac{\partial}{\partial Y} \right) + \frac{1}{B} \sum_{k \leq p} \left( \left( \frac{\partial}{\partial V} \right) Y {}^t \left( \frac{\partial}{\partial V} \right) \right)_{kp}.$$

Moreover,  $\Delta_{n,m;A,B}$  is a differential operator of order 2 which is invariant under the action (1.2) of  $GL_{n,m}$ .

*Proof.* The proof can be found in [14].  $\square$

**Lemma 3.2.** The following volume element  $dv_{n,m}(Y, V)$  on  $\mathcal{P}_{n,m}$  defined by

$$(3.4) \quad dv_{n,m}(Y, V) = (\det Y)^{-\frac{n+m+1}{2}} [dY][dV]$$

is invariant under the action (1.2) of  $GL_{n,m}$ .

*Proof.* The proof can be found in [14].  $\square$

**Theorem 3.1.** Any geodesic through the origin  $(I_n, 0)$  for the Riemannian metric  $ds_{n,m;1,1}^2$  is of the form

$$\gamma(t) = \left( \lambda(2t)[k], Z \left( \int_0^t \lambda(t-s) ds \right) [k] \right),$$

where  $k$  is a fixed element of  $O(n)$ ,  $Z$  is a fixed  $h \times g$  real matrix,  $t$  is a real variable,  $\lambda_1, \lambda_2, \dots, \lambda_n$  are fixed real numbers not all zero and

$$\lambda(t) := \text{diag}(e^{\lambda_1 t}, \dots, e^{\lambda_n t}).$$

Furthermore, the tangent vector  $\gamma'(0)$  of the geodesic  $\gamma(t)$  at  $(I_n, 0)$  is  $(D[k], Z)$ , where  $D = \text{diag}(2\lambda_1, \dots, 2\lambda_n)$ .



*Proof.* The proof can be found in [14]. □

**Theorem 3.2.** *Let  $(Y_0, V_0)$  and  $(Y_1, V_1)$  be two points in  $\mathcal{P}_{n,m}$ . Let  $g$  be an element in  $GL(n, \mathbb{R})$  such that  $Y_0[{}^t g] = I_n$  and  $Y_1[{}^t g]$  is diagonal. Then the length  $s((Y_0, V_0), (Y_1, V_1))$  of the geodesic joining  $(Y_0, V_0)$  and  $(Y_1, V_1)$  for the  $GL_{n,m}$ -invariant Riemannian metric  $ds_{n,m;A,B}^2$  is given by*

$$(3.5) \quad s((Y_0, V_0), (Y_1, V_1)) = A \left\{ \sum_{j=1}^n (\ln t_j)^2 \right\}^{1/2} + B \int_0^1 \left( \sum_{j=1}^n \Delta_j e^{-(\ln t_j)t} \right)^{1/2} dt,$$

where  $\Delta_j = \sum_{k=1}^m \tilde{v}_{kj}^2$  ( $1 \leq j \leq n$ ) with  $(V_1 - V_0)^t g = (\tilde{v}_{kj})$  and  $t_1, \dots, t_n$  denotes the zeros of  $\det(t Y_0 - Y_1)$ .

*Proof.* The proof can be found in [14]. □

The Lie algebra  $\mathfrak{g}_\star$  of  $GL_{n,m}$  is given by

$$\mathfrak{g}_\star = \left\{ (X, Z) \mid X \in \mathbb{R}^{(n,n)}, Z \in \mathbb{R}^{(m,n)} \right\}$$

equipped with the following Lie bracket

$$[(X_1, Z_1), (X_2, Z_2)] = ([X_1, X_2]_0, Z_2 {}^t X_1 - Z_1 {}^t X_2),$$

where  $[X_1, X_2]_0 = X_1 X_2 - X_2 X_1$  denotes the usual matrix bracket and  $(X_1, Z_1), (X_2, Z_2) \in \mathfrak{g}_\star$ . The adjoint representation  $\text{Ad}_\star$  of  $GL_{n,m}$  is given by

$$(3.6) \quad \text{Ad}_\star((g, \lambda))(X, Z) = (gXg^{-1}, (Z - \lambda {}^t X) {}^t g),$$

where  $(g, \lambda) \in GL_{n,m}$  and  $(X, Z) \in \mathfrak{g}_\star$ . Also, the adjoint representation  $\text{ad}_\star$  of  $\mathfrak{g}_\star$  on  $\text{End}(\mathfrak{g}_\star)$  is given by

$$\text{ad}_\star((X, Z))((X_1, Z_1)) = [(X, Z), (X_1, Z_1)].$$

We see that the Killing form  $B_\star$  of  $\mathfrak{g}_\star$  is given by

$$B_\star((X_1, Z_1), (X_2, Z_2)) = (2n + m) \text{tr}(X_1 X_2) - 2 \text{tr}(X_1) \text{tr}(X_2).$$

The Lie algebra  $\mathfrak{k}$  of  $K$  is

$$\mathfrak{k} = \left\{ (X, 0) \in \mathfrak{g}_\star \mid X + {}^t X = 0 \right\}.$$

Let  $\mathfrak{p}_\star$  be the subspace of  $\mathfrak{g}_\star$  defined by

$$\mathfrak{p}_\star = \left\{ (X, Z) \in \mathfrak{g}_\star \mid X = {}^t X \in \mathbb{R}^{(n,n)}, Z \in \mathbb{R}^{(m,n)} \right\}.$$

Then we have the following relations

$$[\mathfrak{k}, \mathfrak{k}] \subset \mathfrak{k} \quad \text{and} \quad [\mathfrak{k}, \mathfrak{p}_\star] \subset \mathfrak{p}_\star.$$

In addition, we have

$$\mathfrak{g}_\star = \mathfrak{k} \oplus \mathfrak{p}_\star \quad (\text{the direct sum}).$$

$K$  acts on  $\mathfrak{p}_*$  via the adjoint representation  $\text{Ad}_*$  of  $GL_{n,m}$  by

$$(3.7) \quad k \cdot (X, Z) = (kX {}^t k, Z {}^t k), \quad k \in K, (X, Z) \in \mathfrak{p}_*.$$

The action (3.7) induces the action of  $K$  on the polynomial algebra  $\text{Pol}(\mathfrak{p}_*)$  of  $\mathfrak{p}_*$  and the symmetric algebra  $S(\mathfrak{p}_*)$ . Denote by  $\text{Pol}(\mathfrak{p}_*)^K$  (resp.,  $S(\mathfrak{p}_*)^K$ ) the subalgebra of  $\text{Pol}(\mathfrak{p}_*)$  (resp.,  $S(\mathfrak{p}_*)$ ) consisting of all  $K$ -invariants. The following inner product  $(\ , \ )_*$  on  $\mathfrak{p}_*$  defined by

$$((X_1, Z_1), (X_2, Z_2))_* = \text{tr}(X_1 X_2) + \text{tr}(Z_1 {}^t Z_2), \quad (X_1, Z_1), (X_2, Z_2) \in \mathfrak{p}_*$$

gives an isomorphism as vector spaces

$$(3.8) \quad \mathfrak{p}_* \cong \mathfrak{p}_*^*, \quad (X, Z) \mapsto f_{X,Z}, \quad (X, Z) \in \mathfrak{p}_*,$$

where  $\mathfrak{p}_*^*$  denotes the dual space of  $\mathfrak{p}_*$  and  $f_{X,Z}$  is the linear functional on  $\mathfrak{p}_*$  defined by

$$f_{X,Z}((X_1, Z_1)) = ((X, Z), (X_1, Z_1))_*, \quad (X_1, Z_1) \in \mathfrak{p}_*.$$

Let  $\mathbb{D}(\mathcal{P}_{n,m})$  be the algebra of all differential operators on  $\mathcal{P}_{n,m}$  that are invariant under the action (1.2) of  $GL_{n,m}$ . It is known that there is a canonical linear bijection of  $S(\mathfrak{p}_*)^K$  onto  $\mathbb{D}(\mathcal{P}_{n,m})$ . Identifying  $\mathfrak{p}_*$  with  $\mathfrak{p}_*^*$  by the above isomorphism (3.5), we get a canonical linear bijection

$$(3.9) \quad \Theta_{n,m} : \text{Pol}(\mathfrak{p}_*)^K \longrightarrow \mathbb{D}(\mathcal{P}_{n,m})$$

of  $\text{Pol}(\mathfrak{p}_*)^K$  onto  $\mathbb{D}(\mathcal{P}_{n,m})$ . The map  $\Theta_{n,m}$  is described explicitly as follows. Put  $N_* = n(n+1)/2 + mn$ . Let  $\{\eta_\alpha \mid 1 \leq \alpha \leq N_*\}$  be a basis of  $\mathfrak{p}_*$ . If  $P \in \text{Pol}(\mathfrak{p}_*)^K$ , then

$$(3.10) \quad (\Theta_{n,m}(P)f)(gK) = \left[ P \left( \frac{\partial}{\partial t_\alpha} \right) f \left( g \exp \left( \sum_{\alpha=1}^{N_*} t_\alpha \eta_\alpha \right) K \right) \right]_{(t_\alpha)=0},$$

where  $f \in C^\infty(\mathcal{P}_{n,m})$ . We refer the reader to [4], pp. 280–289. In general, it is very hard to express  $\Theta_{n,m}(P)$  explicitly for a polynomial  $P \in \text{Pol}(\mathfrak{p}_*)^K$ .

Take a coordinate  $(X, Z)$  in  $\mathfrak{p}_*$  such that

$$X = \begin{pmatrix} x_{11} & \frac{1}{2}x_{12} & \cdots & \frac{1}{2}x_{1n} \\ \frac{1}{2}x_{12} & x_{22} & \cdots & \frac{1}{2}x_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{1}{2}x_{1n} & \frac{1}{2}x_{2n} & \cdots & x_{nn} \end{pmatrix} \in \mathfrak{p} \quad \text{and} \quad Z = (z_{kl}) \in \mathbb{R}^{(m,n)}.$$

Define the polynomials  $\alpha_j, \beta_{pq}^{(k)}, R_{jp}$  and  $S_{jp}$  on  $\mathfrak{p}_*$  by

$$(3.11) \quad \alpha_j(X, Z) = \text{tr}(X^j), \quad 1 \leq j \leq n,$$

$$(3.12) \quad \beta_{pq}^{(k)}(X, Z) = (Z X^k {}^t Z)_{pq}, \quad 0 \leq k \leq n-1, 1 \leq p \leq q \leq m,$$

$$(3.13) \quad R_{jp}(X, Z) = \text{tr}(X^j ({}^t Z Z)^p), \quad 0 \leq j \leq n-1, 1 \leq p \leq m,$$

$$(3.14) \quad S_{jp}(X, Z) = \det(X^j ({}^t Z Z)^p), \quad 0 \leq j \leq n-1, 1 \leq p \leq m,$$

where  $(Z^tZ)_{pq}$  (resp.,  $(ZX^tZ)_{pq}$ ) denotes the  $(p, q)$ -entry of  $Z^tZ$  (resp.,  $ZX^tZ$ ).

For any  $m \times m$  real matrix  $S$ , define the polynomials  $M_{j;S}$ ,  $Q_{p;S}$ ,  $\Omega_{i,p,j;S}$  and  $\Theta_{i,p,j;S}$  on  $\mathfrak{p}_\star$  by

$$(3.15) \quad M_{j;S}(X, Z) = \text{tr}((X + {}^tZSZ)^j), \quad 1 \leq j \leq n,$$

$$(3.16) \quad Q_{p;S}(X, Z) = \text{tr}({}^tZSZ^p), \quad 1 \leq p \leq n,$$

$$(3.17) \quad \Omega_{i,p,j;S}(X, Z) = \text{tr}\left(X^i({}^tZSZ)^p(X + {}^tZSZ)^j\right),$$

$$(3.18) \quad \Theta_{i,p,j;S}(X, Z) = \det\left(X^i({}^tZSZ)^p(X + {}^tZSZ)^j\right),$$

where  $0 \leq i, j \leq n - 1$ ,  $1 \leq p \leq n$ . We see that all  $\alpha_j$ ,  $\beta_{pq}^{(k)}$ ,  $R_{jp}$ ,  $S_{jp}$ ,  $M_{j;S}$ ,  $Q_{p;S}$ ,  $\Omega_{i,p,j;S}$  and  $\Theta_{i,p,j;S}$  are elements of  $\text{Pol}(\mathfrak{p}_\star)^K$ .

We propose the following natural problems.

**Problem 1.** Find a complete list of explicit generators of  $\text{Pol}(\mathfrak{p}_\star)^K$ .

**Problem 2.** Find all relations among a set of generators of  $\text{Pol}(\mathfrak{p}_\star)^K$ .

**Problem 3.** Find an easy or an effective way to express explicitly the images of the above invariant polynomials under the Helgason map  $\Theta_{n,m}$ .

**Problem 4.** Decompose  $\text{Pol}(\mathfrak{p}_\star)^K$  into  $O(n)$ -irreducibles.

**Problem 5.** Find a complete list of explicit generators of the algebra  $\mathbb{D}(\mathcal{P}_{n,m})$  or construct explicit  $GL_{n,m}$ -invariant differential operators on  $\mathcal{P}_{n,m}$ .

**Problem 6.** Find all relations among a set of generators of  $\mathbb{D}(\mathcal{P}_{n,m})$ .

**Problem 7.** Is  $\text{Pol}(\mathfrak{p}_\star)^K$  finitely generated? Is  $\mathbb{D}(\mathcal{P}_{n,m})$  finitely generated?

M. Itoh [6] proved the following theorem.

**Theorem 3.3.** *Pol* $(\mathfrak{p}_\star)^K$  is generated by  $\alpha_j$  ( $1 \leq j \leq n$ ) and  $\beta_{pq}^{(k)}$  ( $0 \leq k \leq n - 1$ ,  $1 \leq p \leq q \leq m$ ).

*Proof.* We refer the reader to Theorem 3.1 in [6]. □

M. Itoh solved Problem 2 in [6], Theorem 3.2.

We present some invariant differential operators on  $\mathcal{P}_{n,m}$ . Define the differential operators  $D_j$ ,  $\Omega_{pq}$  and  $L_p$  on  $\mathcal{P}_{n,m}$  by

$$(3.19) \quad D_j = \text{tr} \left( \left( 2Y \frac{\partial}{\partial Y} \right)^j \right), \quad 1 \leq j \leq n,$$

$$(3.20) \quad \Omega_{pq}^{(k)} = \left\{ \frac{\partial}{\partial V} \left( 2Y \frac{\partial}{\partial Y} \right)^k Y \left( \frac{\partial}{\partial V} \right) \right\}_{pq}, \quad 0 \leq k \leq n - 1, \quad 1 \leq p \leq q \leq m,$$

and

$$(3.21) \quad L_p = \text{tr} \left( \left\{ Y^t \left( \frac{\partial}{\partial V} \right) \frac{\partial}{\partial V} \right\}^p \right), \quad 1 \leq p \leq m.$$

Here, for a matrix  $A$ , we denote by  $A_{pq}$  the  $(p, q)$ -entry of  $A$ .

Also, define the differential operators  $S_{jp}$  by

$$(3.22) \quad S_{jp} = \text{tr} \left( \left( 2Y \frac{\partial}{\partial Y} \right)^j \left\{ Y^t \left( \frac{\partial}{\partial V} \right) \frac{\partial}{\partial V} \right\}^p \right),$$

where  $1 \leq j \leq n$  and  $1 \leq p \leq m$ .

For any real matrix  $S$  of degree  $m$ , define the differential operators  $\Phi_{j;S}$ ,  $L_{p;S}$  and  $\Phi_{i,p,j;S}$  by

$$(3.23) \quad \Phi_{j;S} = \text{tr} \left( \left\{ Y \left( 2 \frac{\partial}{\partial Y} + \left( \frac{\partial}{\partial V} \right)^t S \left( \frac{\partial}{\partial V} \right) \right) \right\}^j \right), \quad 1 \leq j \leq n,$$

$$(3.24) \quad L_{p;S} = \text{tr} \left( \left\{ Y^t \left( \frac{\partial}{\partial V} \right) S \left( \frac{\partial}{\partial V} \right) \right\}^p \right), \quad 1 \leq p \leq m$$

and

$$(3.25) \quad \begin{aligned} &\Phi_{i,p,j;S}(X, Z) \\ &= \text{tr} \left( \left( 2Y \frac{\partial}{\partial Y} \right)^i \left( Y^t \left( \frac{\partial}{\partial V} \right) S \left( \frac{\partial}{\partial V} \right) \right)^p \left\{ Y \left( 2 \frac{\partial}{\partial Y} + \left( \frac{\partial}{\partial V} \right)^t S \left( \frac{\partial}{\partial V} \right) \right) \right\}^j \right). \end{aligned}$$

We want to mention a special invariant differential operator on  $\mathcal{P}_{n,m}$ . In [13], the author studied the following differential operator  $M_{n,m,\mathcal{M}}$  on  $\mathcal{P}_{n,m}$  defined by

$$(3.26) \quad M_{n,m,\mathcal{M}} = \det(Y) \cdot \det \left( \frac{\partial}{\partial Y} + \frac{1}{8\pi} \left( \frac{\partial}{\partial V} \right)^t \mathcal{M}^{-1} \left( \frac{\partial}{\partial V} \right) \right),$$

where  $\mathcal{M}$  is a positive definite, symmetric half-integral matrix of degree  $m$ . This differential operator characterizes *singular Jacobi forms*. For more detail, we refer the reader to [13]. From (3.1) and (3.2), we can easily see that the differential operator  $M_{n,m,\mathcal{M}}$  is invariant under the action (1.2) of  $GL_{n,m}$ .

**Question.** Calculate the inverse of  $M_{n,m,\mathcal{M}}$  under the Helgason map  $\Theta_{n,m}$ .

#### 4. The case when $n = 1$

In this section, we consider the case when  $n = m = 1$  and the case when  $n = 1$  and  $m \geq 2$  separately.

##### 4.1. The case when $n = 1$ and $m = 1$

In this case,

$$GL_{1,1} = \mathbb{R}^\times \ltimes \mathbb{R}, \quad K = O(1), \quad \mathcal{P}_{1,1} = \mathbb{R}^+ \times \mathbb{R},$$

where  $\mathbb{R}^\times = \{a \in \mathbb{R} \mid a \neq 0\}$  and  $\mathbb{R}^+ = \{a \in \mathbb{R} \mid a > 0\}$ . Clearly,  $\mathfrak{k} = 0$  and  $\mathfrak{p}_* = \mathfrak{g}_* = \{(x, z) \mid x, z \in \mathbb{R}\}$ . Then  $e = (1, 0)$  and  $f = (0, 1)$  form the standard basis for  $\mathfrak{p}_*$ . Using this basis, we take a coordinate  $(x, z)$  in  $\mathfrak{p}_*$ ; that is, if  $w \in \mathfrak{p}_*$ , then we write  $w = xe + zf$ . We can show that  $\text{Pol}(\mathfrak{p}_*)^K$  is generated by the following polynomials

$$\alpha(x, z) = x \quad \text{and} \quad \beta(x, z) = z^2.$$

The generators  $\alpha$  and  $\beta$  are *algebraically independent*. Let  $(y, v)$  be a coordinate in  $\mathcal{P}_{1,1}$  with  $y > 0$  and  $v \in \mathbb{R}$ . Then using Formula (3.10), we can show that

$$\Theta_{1,1}(\alpha) = 2y \frac{\partial}{\partial y} \quad \text{and} \quad \Theta_{1,1}(\beta) = y \frac{\partial^2}{\partial v^2}.$$

We see that  $\Theta_{1,1}(\alpha)$  and  $\Theta_{1,1}(\beta)$  generate the algebra  $\mathbb{D}(\mathcal{P}_{1,1})$  and are *algebraically dependent*. Indeed, we have the following noncommutation relation

$$\Theta_{1,1}(\alpha)\Theta_{1,1}(\beta) - \Theta_{1,1}(\beta)\Theta_{1,1}(\alpha) = 2\Theta_{1,1}(\beta).$$

Hence the algebra  $\mathbb{D}(\mathcal{P}_{1,1})$  is *not* commutative. The unitary dual  $\widehat{K}$  of  $K$  consists of two elements. Let

$$\text{Pol}(\mathfrak{p}_*) = \sum_{\tau \in \widehat{K}} m_\tau \tau$$

be the decomposition of  $\text{Pol}(\mathfrak{p}_*)$  into  $K$ -irreducibles. It is easy to see that the multiplicity  $m_\tau$  of  $\tau$  is infinite for all  $\tau \in \widehat{K}$ . So the action of  $K$  on  $\text{Pol}(\mathfrak{p}_*)$  is not multiplicity-free. In this case, the seven problems proposed in Section 3 are completely solved.

#### 4.2. The case when $n = 1$ and $m \geq 2$

Consider the case when  $n = 1$  and  $m \geq 2$ . In this case,

$$GL_{1,m} = \mathbb{R}^\times \ltimes \mathbb{R}^{(m,1)}, \quad K = O(1), \quad \mathcal{P}_{1,m} = \mathbb{R}^+ \times \mathbb{R}^{(m,1)},$$

where  $\mathbb{R}^\times = \{a \in \mathbb{R} \mid a \neq 0\}$  and  $\mathbb{R}^+ = \{a \in \mathbb{R} \mid a > 0\}$ . Clearly,  $\mathfrak{k} = 0$  and  $\mathfrak{p}_* = \mathfrak{g}_* = \{(x, z) \mid x \in \mathbb{R}, z \in \mathbb{R}^{(m,1)}\}$ . Let  $\{e_1, \dots, e_m\}$  be the standard basis of  $\mathbb{R}^{(m,1)}$ . Then

$$\eta_0 = (1, 0), \quad \eta_1 = (0, e_1), \quad \eta_2 = (0, e_2), \dots, \quad \eta_m = (0, e_m)$$

form a basis of  $\mathfrak{p}_*$ . Using this basis, we take a coordinate  $(x, z_1, z_2, \dots, z_m)$  in  $\mathfrak{p}_*$ ; that is, if  $w \in \mathfrak{p}_*$ , then we write  $w = x\eta_0 + \sum_{k=1}^m z_k \eta_k$ . We can show that  $\text{Pol}(\mathfrak{p}_*)^K$  is generated by the following polynomials

$$\alpha(x, z) = x \quad \text{and} \quad \beta_{kl}(x, z) = z_k z_l, \quad 1 \leq k \leq l \leq m,$$

where  $z = (z_1, z_2, \dots, z_m)$ . We see easily that one has the following relations

$$\beta_{kk}\beta_{ll} = \beta_{kl}^2 \quad \text{for } 1 \leq k < l \leq m$$

and

$$\beta_{kk}\beta_{ll}^2\beta_{pp} = \beta_{kl}^2\beta_{lp}^2 \quad \text{for } 1 \leq k < l < p \leq m.$$

Therefore, the generators  $\alpha$  and  $\beta_{kl}$  ( $1 \leq k \leq l \leq m$ ) are *algebraically dependent*.

Let  $(y, v)$  be a coordinate in  $\mathcal{P}_{1,m}$  with  $y > 0$  and  $v = {}^t(v_1, v_2, \dots, v_m) \in \mathbb{R}^{(m,1)}$ . Then using Formula (3.10), we can show that

$$\Theta_{1,m}(\alpha) = 2y \frac{\partial}{\partial y} \quad \text{and} \quad \Theta_{1,m}(\beta_{kl}) = y \frac{\partial^2}{\partial v_k \partial v_l}, \quad 1 \leq k \leq l \leq m.$$

We see that  $\Theta_{1,m}(\alpha)$  and  $\Theta_{1,m}(\beta_{kl})$  ( $1 \leq k \leq l \leq m$ ) generate the algebra  $\mathbb{D}(\mathcal{P}_{1,m})$ . Although  $\Theta_{1,m}(\beta_{kl})$  ( $1 \leq k \leq l \leq m$ ) commute with each other,  $\Theta_{1,m}(\alpha)$  does not commute with any  $\Theta_{1,m}(\beta_{kl})$ . Indeed, we have the noncommutation relation

$$\Theta_{1,m}(\alpha)\Theta_{1,m}(\beta_{kl}) - \Theta_{1,m}(\beta_{kl})\Theta_{1,m}(\alpha) = 2\Theta_{1,m}(\beta_{kl}).$$

Hence the algebra  $\mathbb{D}(\mathcal{P}_{1,m})$  is *not* commutative. It is easily seen that the action of  $K$  on  $\text{Pol}(\mathfrak{p}_\star)$  is *not* multiplicity-free.

### 5. The case when $n = 2$

In this section, we deal with the case when  $n = 2$ ,  $m = 1$  and the case when  $n = m = 2$ .

#### 5.1. The case when $n = 2$ and $m = 1$

In this case,

$$GL_{2,1} = GL(2, \mathbb{R}) \times \mathbb{R}^{(1,2)}, \quad K = O(2) \quad \text{and} \quad GL_{2,1}/K = \mathcal{P}_2 \times \mathbb{R}^{(1,2)} = \mathcal{P}_{2,1}.$$

We see easily that

$$\mathfrak{p}_\star = \left\{ (X, Z) \mid X = {}^tX \in \mathbb{R}^{(2,2)}, \quad Z \in \mathbb{R}^{(1,2)} \right\}.$$

Put

$$e_1 = \left( \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, 0 \right), \quad e_2 = \left( \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}, 0 \right), \quad e_3 = \left( \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, 0 \right)$$

and

$$f_1 = (0, (1, 0)), \quad f_2 = (0, (0, 1)).$$

Then  $\{e_1, e_2, e_3, f_1, f_2\}$  forms a basis for  $\mathfrak{p}_\star$ . For variables  $(X, Z) \in \mathfrak{p}_\star$ , write

$$X = \begin{pmatrix} x_1 & \frac{1}{2}x_3 \\ \frac{1}{2}x_3 & x_2 \end{pmatrix} \quad \text{and} \quad Z = (z_1, z_2).$$

The following polynomials

$$\alpha_1(X, Z) = \text{tr}(X) = x_1 + x_2, \quad \alpha_2(X, Z) = \text{tr}(X^2) = x_1^2 + x_2^2 + \frac{1}{2}x_3^2,$$

$$\xi(X, Z) = Z {}^tZ = z_1^2 + z_2^2$$

and

$$\varphi(X, Z) = ZX^tZ = x_1 z_1^2 + x_2 z_2^2 + x_3 z_1 z_2$$

generate the algebra  $\text{Pol}(\mathfrak{p}_\star)^K$ . We can show that the invariants  $\alpha_1, \alpha_2, \xi$  and  $\varphi$  are *algebraically independent*. We omit the detail.

Now we compute the  $GL_{2,1}$ -invariant differential operators  $D_1, D_2, \Psi, \Delta$  on  $\mathcal{P}_{2,1}$  corresponding to the  $K$ -invariants  $\alpha_1, \alpha_2, \xi, \varphi$ , respectively, under a canonical linear bijection

$$\Theta_{2,1} : \text{Pol}(\mathfrak{p}_\star)^K \longrightarrow \mathbb{D}(\mathcal{P}_{2,1}).$$

For real variables  $t = (t_1, t_2, t_3)$  and  $s = (s_1, s_2)$ , we have

$$\begin{aligned} & \exp(t_1 e_1 + t_2 e_2 + t_3 e_3 + s_1 f_1 + s_2 f_2) \\ &= \left( \begin{pmatrix} a_1(t, s) & a_3(t, s) \\ a_3(t, s) & a_2(t, s) \end{pmatrix}, (b_1(t, s), b_2(t, s)) \right), \end{aligned}$$

where

$$\begin{aligned} a_1(t, s) &= 1 + t_1 + \frac{1}{2!}(t_1^2 + t_3^2) + \frac{1}{3!}(t_1^3 + 2t_1 t_3^2 + t_2 t_3^2) + \dots, \\ a_2(t, s) &= 1 + t_2 + \frac{1}{2!}(t_2^2 + t_3^2) + \frac{1}{3!}(t_1 t_3^2 + 2t_2 t_3^2 + t_3^3) + \dots, \\ a_3(t, s) &= t_3 + \frac{1}{2!}(t_1 + t_2)t_3 + \frac{1}{3!}(t_1 t_2 + t_1^2 + t_2^2 + t_3^2)t_3 + \dots, \\ b_1(t, s) &= s_1 - \frac{1}{2!}(s_1 t_1 + s_2 t_3) + \frac{1}{3!} \{ s_1(t_1^2 + t_3^2) + s_2(t_1 t_3 + t_2 t_3) \} - \dots, \\ b_2(t, s) &= s_2 - \frac{1}{2!}(s_1 t_3 + s_2 t_2) + \frac{1}{3!} \{ s_1(t_1 + t_2)t_3 + s_2(t_2^2 + t_3^2) \} - \dots. \end{aligned}$$

For brevity, we write  $a_i, b_k$  for  $a_i(t, s), b_k(t, s)$  ( $i = 1, 2, 3, k = 1, 2$ ), respectively. We now fix an element  $(g, c) \in GL_{2,1}$  and write

$$g = \begin{pmatrix} g_1 & g_{12} \\ g_{21} & g_2 \end{pmatrix} \quad \text{and} \quad c = (c_1, c_2).$$

Put

$$(Y(t, s), V(t, s)) = \left( (g, c) \cdot \exp \left( \sum_{i=1}^3 t_i e_i + \sum_{k=1}^2 s_k f_k \right) \right) \cdot (I_2, 0)$$

with

$$Y(t, s) = \begin{pmatrix} y_1(t, s) & y_3(t, s) \\ y_3(t, s) & y_2(t, s) \end{pmatrix} \quad \text{and} \quad V(t, s) = (v_1(t, s), v_2(t, s)).$$

By an easy computation, we obtain

$$\begin{aligned} y_1 &= (g_1 a_1 + g_{12} a_3)^2 + (g_1 a_3 + g_{12} a_2)^2, \\ y_2 &= (g_{21} a_1 + g_2 a_3)^2 + (g_{21} a_3 + g_2 a_2)^2, \\ y_3 &= (g_1 a_1 + g_{12} a_3)(g_{21} a_1 + g_2 a_3) + (g_1 a_3 + g_{12} a_2)(g_{21} a_3 + g_2 a_2), \end{aligned}$$

$$\begin{aligned} v_1 &= (c_1 + b_1 a_1 + b_2 a_3)g_1 + (c_2 + b_1 a_3 + b_2 a_2)g_{12}, \\ v_2 &= (c_1 + b_1 a_1 + b_2 a_3)g_{21} + (c_2 + b_1 a_3 + b_2 a_2)g_2. \end{aligned}$$

Using the chain rule, we can easily compute the  $GL_{2,1}$ -invariant differential operators  $D_1 = \Theta_{2,1}(\alpha_1)$ ,  $D_2 = \Theta_{2,1}(\alpha_2)$ ,  $\Psi = \Theta_{2,1}(\xi)$  and  $\Delta = \Theta_{2,1}(\varphi)$ . They are given by

$$\begin{aligned} D_1 &= 2 \operatorname{tr} \left( Y \frac{\partial}{\partial Y} \right) = 2 \left( y_1 \frac{\partial}{\partial y_1} + y_2 \frac{\partial}{\partial y_2} + y_3 \frac{\partial}{\partial y_3} \right), \\ D_2 &= \operatorname{tr} \left( \left( 2Y \frac{\partial}{\partial Y} \right)^2 \right) \\ &= 3 D_1 + 8 \left( y_3^2 \frac{\partial^2}{\partial y_1 \partial y_2} + y_1 y_3 \frac{\partial^2}{\partial y_1 \partial y_3} + y_2 y_3 \frac{\partial^2}{\partial y_2 \partial y_3} \right) \\ &\quad + 4 \left\{ y_1^2 \frac{\partial^2}{\partial y_1^2} + y_2^2 \frac{\partial^2}{\partial y_2^2} + \frac{1}{2} (y_1 y_2 + y_3^2) \frac{\partial^2}{\partial y_3^2} \right\}, \\ \Psi &= \operatorname{tr} \left( Y {}^t \left( \frac{\partial}{\partial V} \right) \left( \frac{\partial}{\partial V} \right) \right) \\ &= y_1 \frac{\partial^2}{\partial v_1^2} + 2y_3 \frac{\partial^2}{\partial v_1 \partial v_2} + y_2 \frac{\partial^2}{\partial v_2^2} \end{aligned}$$

and

$$\begin{aligned} \Delta &= \frac{\partial}{\partial V} \left( 2Y \frac{\partial}{\partial Y} \right) Y {}^t \left( \frac{\partial}{\partial V} \right) \\ &= 2 \left( y_1^2 \frac{\partial^3}{\partial y_1 \partial v_1^2} + 2 y_1 y_3 \frac{\partial^3}{\partial y_1 \partial v_1 \partial v_2} + y_3^2 \frac{\partial^3}{\partial y_1 \partial v_2^2} \right) \\ &\quad + 2 \left( y_3^2 \frac{\partial^3}{\partial y_2 \partial v_1^2} + 2 y_2 y_3 \frac{\partial^3}{\partial y_2 \partial v_1 \partial v_2} + y_2^2 \frac{\partial^3}{\partial y_2 \partial v_2^2} \right) \\ &\quad + 2 \left\{ y_1 y_3 \frac{\partial^3}{\partial y_3 \partial v_1^2} + (y_1 y_2 + y_3^2) \frac{\partial^3}{\partial y_3 \partial v_1 \partial v_2} + y_2 y_3 \frac{\partial^3}{\partial y_3 \partial v_2^2} \right\} \\ &\quad + 3 \left( y_1 \frac{\partial^2}{\partial v_1^2} + 2y_3 \frac{\partial^2}{\partial v_1 \partial v_2} + y_2 \frac{\partial^2}{\partial v_2^2} \right). \end{aligned}$$

Clearly,  $D_1$  commutes with  $D_2$  but  $\Psi$  does not commute with  $D_1$  nor with  $D_2$ . Indeed, we have the following noncommutation relations

$$[D_1, \Psi] = D_1 \Psi - \Psi D_1 = 2 \Psi$$

and

$$\begin{aligned} [D_2, \Psi] &= D_2 \Psi - \Psi D_2 \\ &= 2(2D_1 - 1)\Psi - 8 \det(Y) \cdot \det \left( \frac{\partial}{\partial Y} + {}^t \left( \frac{\partial}{\partial V} \right) \frac{\partial}{\partial V} \right) \end{aligned}$$



$$+ 8 \det(Y) \cdot \det\left(\frac{\partial}{\partial Y}\right) - 4(y_1 y_2 + y_3^2) \frac{\partial^3}{\partial y_3 \partial v_1 \partial v_2}.$$

Hence the algebra  $\mathbb{D}(\mathcal{P}_{2,1})$  is *not* commutative.

## 5.2. The case when $n = 2$ and $m = 2$

In this case,

$$GL_{2,2} = GL(2, \mathbb{R}) \times \mathbb{R}^{(2,2)}, \quad K = O(2) \quad \text{and} \quad GL_{2,2}/K = \mathcal{P}_2 \times \mathbb{R}^{(2,2)} = \mathcal{P}_{2,2}.$$

We see easily that

$$\mathfrak{p}_* = \left\{ (X, Z) \mid X = {}^t X \in \mathbb{R}^{(2,2)}, \quad Z \in \mathbb{R}^{(2,2)} \right\}.$$

Let  $O_2$  be the  $2 \times 2$  zero matrix. Put

$$e_1 = \left( \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, O_2 \right), \quad e_2 = \left( \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}, O_2 \right), \quad e_3 = \left( \begin{pmatrix} 0 & \frac{1}{2} \\ \frac{1}{2} & 0 \end{pmatrix}, O_2 \right)$$

and

$$\begin{aligned} f_1 &= \left( O_2, \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \right), \quad f_2 = \left( O_2, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \right), \\ f_3 &= \left( O_2, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \right), \quad f_4 = \left( O_2, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right). \end{aligned}$$

Then  $\{e_1, e_2, e_3, f_1, f_2, f_3, f_4\}$  forms a basis for  $\mathfrak{p}_*$ . For variables  $(X, Z) \in \mathfrak{p}_*$ , write

$$X = \begin{pmatrix} x_1 & \frac{1}{2}x_3 \\ \frac{1}{2}x_3 & x_2 \end{pmatrix} \quad \text{and} \quad Z = \begin{pmatrix} z_{11} & z_{12} \\ z_{21} & z_{22} \end{pmatrix}.$$

From Theorem 3.3, the algebra  $\text{Pol}(\mathfrak{p}_*)^K$  is generated by the following polynomials

$$\begin{aligned} \alpha_1(X, Z) &= \text{tr}(X) = x_1 + x_2, \\ \alpha_2(X, Z) &= \text{tr}(X^2) = x_1^2 + x_2^2 + \frac{1}{2}x_3^2, \\ \beta_{11}^{(0)}(X, Z) &= (Z {}^t Z)_{11} = z_{11}^2 + z_{12}^2, \\ \beta_{12}^{(0)}(X, Z) &= (Z {}^t Z)_{12} = z_{11}z_{21} + z_{12}z_{22}, \\ \beta_{22}^{(0)}(X, Z) &= (Z {}^t Z)_{22} = z_{21}^2 + z_{22}^2, \\ \beta_{11}^{(1)}(X, Z) &= (ZX {}^t Z)_{11} = x_1 z_{11}^2 + x_2 z_{12}^2 + x_3 z_{11}z_{12}, \\ \beta_{12}^{(1)}(X, Z) &= (ZX {}^t Z)_{12} = x_1 z_{11}z_{21} + x_2 z_{12}z_{22} + \frac{1}{2}x_3(z_{11}z_{22} + z_{12}z_{21}), \\ \beta_{22}^{(1)}(X, Z) &= (ZX {}^t Z)_{22} = x_1 z_{21}^2 + x_2 z_{22}^2 + x_3 z_{21}z_{22}. \end{aligned}$$

Set

$$\Delta_{ab} := \det \begin{pmatrix} \beta_{11}^{(a)} & \beta_{12}^{(b)} \\ \beta_{12}^{(a)} & \beta_{22}^{(b)} \end{pmatrix} \quad \text{for } a, b = 0, 1.$$

By a direct computation, we can show that the following equation

$$(5.1) \quad \alpha_1 \Delta_{00} - \Delta_{01} - \Delta_{10} = 0$$

holds.

We take a coordinate  $(Y, V)$  in  $\mathcal{P}_{2,2}$ , that is,

$$Y = \begin{pmatrix} y_1 & y_3 \\ y_3 & y_2 \end{pmatrix} \quad \text{and} \quad V = \begin{pmatrix} v_{11} & v_{12} \\ v_{21} & v_{22} \end{pmatrix}.$$

Put

$$\frac{\partial}{\partial Y} = \begin{pmatrix} \frac{\partial}{\partial y_1} & \frac{1}{2} \frac{\partial}{\partial y_3} \\ \frac{1}{2} \frac{\partial}{\partial y_3} & \frac{\partial}{\partial y_2} \end{pmatrix} \quad \text{and} \quad \frac{\partial}{\partial V} = \begin{pmatrix} \frac{\partial}{\partial v_{11}} & \frac{\partial}{\partial v_{12}} \\ \frac{\partial}{\partial v_{21}} & \frac{\partial}{\partial v_{22}} \end{pmatrix}.$$

Consider the following differential operators

$$D_i := \text{tr} \left( \left( 2Y \frac{\partial}{\partial Y} \right)^i \right), \quad i = 1, 2$$

and

$$\Omega_{pq}^{(k)} = \left\{ \frac{\partial}{\partial V} \left( 2Y \frac{\partial}{\partial Y} \right)^k Y \left( \frac{\partial}{\partial V} \right) \right\}_{pq}, \quad k = 0, 1, \quad 1 \leq p \leq q \leq 2.$$

Note that  $D_1, D_2, \Omega_{11}^{(0)}, \dots, \Omega_{22}^{(1)}$  are  $GL_{2,2}$ -invariant. For brevity, we put

$$\partial_{ij} = \frac{\partial}{\partial v_{ij}}, \quad i, j = 1, 2.$$

It is easily seen that

$$\begin{aligned} D_1 &= \text{tr} \left( 2Y \frac{\partial}{\partial Y} \right) = 2 \sum_{i=1}^3 y_i \frac{\partial}{\partial y_i}, \\ D_2 &= 3D_1 + 8 \left( y_3^2 \frac{\partial^2}{\partial y_1 \partial y_2} + y_1 y_3 \frac{\partial^2}{\partial y_1 \partial y_3} + y_2 y_3 \frac{\partial^2}{\partial y_2 \partial y_3} \right) \\ &\quad + 4 \left\{ y_1^2 \frac{\partial^2}{\partial y_1^2} + y_2^2 \frac{\partial^2}{\partial y_2^2} + \frac{1}{2} (y_1 y_2 + y_3^2) \frac{\partial^2}{\partial y_3^2} \right\}, \\ \Omega_{11}^{(0)} &= y_1 \partial_{11}^2 + y_2 \partial_{12}^2 + 2 y_3 \partial_{11} \partial_{12}, \\ \Omega_{12}^{(0)} &= y_1 \partial_{11} \partial_{21} + y_2 \partial_{12} \partial_{22} + y_3 (\partial_{11} \partial_{22} + \partial_{12} \partial_{21}), \\ \Omega_{22}^{(0)} &= y_1 \partial_{21}^2 + y_2 \partial_{22}^2 + 2 y_3 \partial_{21} \partial_{22}. \end{aligned}$$

Then by a direct computation, we have the following relations

$$(5.2) \quad [D_1, D_2] = 0,$$

$$(5.3) \quad [\Omega_{kl}^{(0)}, \Omega_{pq}^{(0)}] = 0, \quad 1 \leq k \leq l \leq 2, \quad 1 \leq p \leq q \leq 2,$$

$$(5.4) \quad [D_1, \Omega_{11}^{(0)}] = 2\Omega_{11}^{(0)}, \quad [D_1, \Omega_{12}^{(0)}] = 2\Omega_{12}^{(0)}, \quad [D_1, \Omega_{22}^{(0)}] = 2\Omega_{22}^{(0)}.$$

Therefore,  $\mathbb{D}(\mathcal{P}_{2,2})$  is not commutative.

## 6. The case when $n = 3$

### 6.1. The case when $n = 3$ and $m = 1$

In this case,

$$GL_{3,1} = GL(3, \mathbb{R}) \times \mathbb{R}^{(1,3)}, \quad K = O(3) \quad \text{and} \quad GL_{3,1}/K = \mathcal{P}_3 \times \mathbb{R}^{(1,3)} = \mathcal{P}_{3,1}.$$

We see easily that

$$\mathfrak{p}_* = \left\{ (X, Z) \mid X = {}^t X \in \mathbb{R}^{(3,3)}, \quad Z \in \mathbb{R}^{(1,3)} \right\}.$$

Put

$$\begin{aligned} E_1 &= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, & E_2 &= \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}, & E_3 &= \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \\ E_4 &= \begin{pmatrix} 0 & \frac{1}{2} & 0 \\ \frac{1}{2} & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, & E_5 &= \begin{pmatrix} 0 & 0 & \frac{1}{2} \\ 0 & 0 & 0 \\ \frac{1}{2} & 0 & 0 \end{pmatrix}, & E_6 &= \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & \frac{1}{2} \\ 0 & \frac{1}{2} & 0 \end{pmatrix}. \end{aligned}$$

Let  $O_3$  be the  $3 \times 3$  zero matrix and let  $O_{1,3} = (0, 0, 0) \in \mathbb{R}^{(1,3)}$ . Put

$$e_i = (E_i, O_{1,3}), \quad 1 \leq i \leq 6,$$

$$f_1 = (O_3, (1, 0, 0)), \quad f_2 = (O_3, (0, 1, 0)), \quad f_3 = (O_3, (0, 0, 1)).$$

Then  $\{e_i, f_j \mid 1 \leq i \leq 6, \quad 1 \leq j \leq 3\}$  forms a basis for  $\mathfrak{p}_*$ . Using this basis, we write for variables  $(X, Z) \in \mathfrak{p}_*$ ,

$$X = \begin{pmatrix} x_1 & \frac{1}{2}x_4 & \frac{1}{2}x_5 \\ \frac{1}{2}x_4 & x_2 & \frac{1}{2}x_6 \\ \frac{1}{2}x_5 & \frac{1}{2}x_6 & x_3 \end{pmatrix} \quad \text{and} \quad Z = (z_1, z_2, z_3).$$

From Theorem 3.3, the algebra  $\text{Pol}(\mathfrak{p}_*)^K$  is generated by the following polynomials

$$\alpha_1(X, Z) = x_1 + x_2 + x_3,$$

$$\alpha_2(X, Z) = x_1^2 + x_2^2 + x_3^2 + \frac{1}{2}(x_4^2 + x_5^2 + x_6^2),$$

$$\begin{aligned} \alpha_3(X, Z) &= x_1^3 + x_2^3 + x_3^3 + \frac{3}{4} \{ (x_1 + x_2)x_4^2 + (x_1 + x_3)x_5^2 + (x_2 + x_3)x_6^2 \} \\ &\quad + \frac{3}{4} x_4 x_5 x_6, \end{aligned}$$

$$\beta_0(X, Z) = z_1^2 + z_2^2 + z_3^2,$$

$$\begin{aligned}\beta_1(X, Z) &= x_1 z_1^2 + x_2 z_2^2 + x_3 z_3^2 + x_4 z_1 z_2 + x_5 z_1 z_3 + x_6 z_2 z_3, \\ \beta_2(X, Z) &= x_1^2 z_1^2 + x_2^2 z_2^2 + \frac{1}{4} \{ (x_4^2 + x_5^2) z_1^2 + (x_4^2 + x_6^2) z_2^2 + (x_5^2 + x_6^2) z_3^2 \} \\ &\quad + \left( x_1 x_4 + x_2 x_4 + \frac{1}{2} x_5 x_6 \right) z_1 z_2 + \left( x_1 x_5 + x_3 x_5 + \frac{1}{2} x_4 x_6 \right) z_1 z_3 \\ &\quad + \left( x_2 x_6 + x_3 x_6 + \frac{1}{2} x_4 x_5 \right) z_2 z_3.\end{aligned}$$

We take a coordinate  $(Y, V)$  in  $\mathcal{P}_{3,1}$ , that is,

$$Y = \begin{pmatrix} y_1 & y_4 & y_5 \\ y_4 & y_2 & y_6 \\ y_5 & y_6 & y_3 \end{pmatrix} \quad \text{and} \quad V = (v_1, v_2, v_3).$$

Put

$$\frac{\partial}{\partial Y} = \begin{pmatrix} \frac{\partial}{\partial y_1} & \frac{1}{2} \frac{\partial}{\partial y_4} & \frac{1}{2} \frac{\partial}{\partial y_5} \\ \frac{1}{2} \frac{\partial}{\partial y_4} & \frac{\partial}{\partial y_2} & \frac{1}{2} \frac{\partial}{\partial y_6} \\ \frac{1}{2} \frac{\partial}{\partial y_5} & \frac{1}{2} \frac{\partial}{\partial y_6} & \frac{\partial}{\partial y_3} \end{pmatrix} \quad \text{and} \quad \frac{\partial}{\partial V} = \left( \frac{\partial}{\partial v_1}, \frac{\partial}{\partial v_2}, \frac{\partial}{\partial v_3} \right).$$

Consider the following differential operators

$$D_i := \text{tr} \left( \left( 2Y \frac{\partial}{\partial Y} \right)^i \right), \quad i = 1, 2, 3$$

and

$$\Omega_k = \frac{\partial}{\partial V} \left( 2Y \frac{\partial}{\partial Y} \right)^k Y \left( \frac{\partial}{\partial V} \right), \quad k = 0, 1, 2.$$

Note that  $D_1, D_2, D_3, \Omega_0, \Omega_1$  and  $\Omega_2$  are  $GL_{2,2}$ -invariant. It is easily seen that

$$\begin{aligned}D_1 &= \text{tr} \left( 2Y \frac{\partial}{\partial Y} \right) = 2 \sum_{i=1}^6 y_i \frac{\partial}{\partial y_i}, \\ \Omega_0 &= y_1 \frac{\partial^2}{\partial v_1^2} + y_2 \frac{\partial^2}{\partial v_2^2} + y_3 \frac{\partial^2}{\partial v_3^2} \\ &\quad + 2y_4 \frac{\partial^2}{\partial v_1 \partial v_2} + 2y_5 \frac{\partial^2}{\partial v_1 \partial v_3} + 2y_6 \frac{\partial^2}{\partial v_2 \partial v_3}.\end{aligned}$$

Then we have the following relations

$$(6.1) \quad [D_i, D_j] = 0 \quad \text{for all } i, j = 1, 2, 3$$

and

$$(6.2) \quad [D_1, \Omega_0] = 2\Omega_0.$$

Therefore,  $\mathbb{D}(\mathcal{P}_{3,1})$  is not commutative.

## 6.2. The case when $n = 3$ and $m = 2$

In this case,

$$GL_{3,2} = GL(3, \mathbb{R}) \ltimes \mathbb{R}^{(2,3)}, \quad K = O(3) \quad \text{and} \quad GL_{3,2}/K = \mathcal{P}_3 \times \mathbb{R}^{(2,3)} = \mathcal{P}_{3,2}.$$

We see easily that

$$\mathfrak{p}_\star = \left\{ (X, Z) \mid X = {}^t X \in \mathbb{R}^{(3,3)}, \quad Z \in \mathbb{R}^{(2,3)} \right\}.$$

Put

$$\begin{aligned} E_1 &= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, & E_2 &= \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}, & E_3 &= \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \\ E_4 &= \begin{pmatrix} 0 & \frac{1}{2} & 0 \\ \frac{1}{2} & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, & E_5 &= \begin{pmatrix} 0 & 0 & \frac{1}{2} \\ 0 & 0 & 0 \\ \frac{1}{2} & 0 & 0 \end{pmatrix}, & E_6 &= \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & \frac{1}{2} \\ 0 & \frac{1}{2} & 0 \end{pmatrix}. \end{aligned}$$

and

$$\begin{aligned} F_1 &= \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, & F_2 &= \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}, & F_3 &= \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}, \\ F_4 &= \begin{pmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}, & F_5 &= \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}, & F_6 &= \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}. \end{aligned}$$

Let  $O_3$  be the  $3 \times 3$  zero matrix and let

$$O_{2,3} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \in \mathbb{R}^{(2,3)}.$$

Put

$$e_i = (E_i, O_{2,3}), \quad f_j = (O_3, F_j) \quad 1 \leq i, j \leq 6.$$

Then  $\{e_i, f_j \mid 1 \leq i, j \leq 6\}$  forms a basis for  $\mathfrak{p}_\star$ . Using this basis, we write for variables  $(X, Z) \in \mathfrak{p}_\star$ ,

$$X = \begin{pmatrix} x_1 & \frac{1}{2}x_4 & \frac{1}{2}x_5 \\ \frac{1}{2}x_4 & x_2 & \frac{1}{2}x_6 \\ \frac{1}{2}x_5 & \frac{1}{2}x_6 & x_3 \end{pmatrix} \quad \text{and} \quad Z = \begin{pmatrix} z_{11} & z_{12} & z_{13} \\ z_{21} & z_{22} & z_{23} \end{pmatrix}.$$

From Theorem 3.3, the algebra  $\text{Pol}(\mathfrak{p}_\star)^K$  is generated by the following polynomials

$$\alpha_1(X, Z) = x_1 + x_2 + x_3,$$

$$\alpha_2(X, Z) = x_1^2 + x_2^2 + x_3^2 + \frac{1}{2}(x_4^2 + x_5^2 + x_6^2),$$

$$\begin{aligned} \alpha_3(X, Z) &= x_1^3 + x_2^3 + x_3^3 + \frac{3}{4} \left\{ (x_1 + x_2)x_4^2 + (x_1 + x_3)x_5^2 + (x_2 + x_3)x_6^2 \right\} \\ &\quad + \frac{3}{4} x_4 x_5 x_6, \end{aligned}$$

$$\beta_{11}^{(0)}(X, Z) = z_{11}^2 + z_{12}^2 + z_{13}^2,$$

$$\beta_{12}^{(0)}(X, Z) = z_{11}z_{21} + z_{12}z_{22} + z_{13}z_{23},$$

$$\begin{aligned}
\beta_{22}^{(0)}(X, Z) &= z_{21}^2 + z_{22}^2 + z_{23}^2, \\
\beta_{11}^{(1)}(X, Z) &= x_1 z_{11}^2 + x_2 z_{12}^2 + x_3 z_{13}^2 + x_4 z_{11} z_{12} + x_5 z_{11} z_{13} + x_6 z_{12} z_{13}, \\
\beta_{12}^{(1)}(X, Z) &= x_1 z_{11} z_{21} + x_2 z_{12} z_{22} + x_3 z_{13} z_{23} + \frac{1}{2} x_4 (z_{11} z_{22} + z_{12} z_{21}) \\
&\quad + \frac{1}{2} x_5 (z_{11} z_{23} + z_{13} z_{21}) + \frac{1}{2} x_6 (z_{12} z_{23} + z_{13} z_{22}), \\
\beta_{22}^{(1)}(X, Z) &= x_1 z_{21}^2 + x_2 z_{22}^2 + x_3 z_{23}^2 + x_4 z_{21} z_{22} + x_5 z_{21} z_{23} + x_6 z_{22} z_{23}, \\
\beta_{11}^{(2)}(X, Z) &= x_1^2 z_{11}^2 + x_2^2 z_{12}^2 + x_3^2 z_{13}^2 \\
&\quad + \frac{1}{4} \{ x_4^2 (z_{11}^2 + z_{12}^2) + x_5^2 (z_{11}^2 + z_{13}^2) + x_6^2 (z_{12}^2 + z_{13}^2) \} \\
&\quad + (x_1 + x_2) x_4 z_{11} z_{12} + (x_1 + x_3) x_5 z_{11} z_{13} + (x_2 + x_3) x_6 z_{12} z_{13} \\
&\quad + \frac{1}{2} (x_4 x_5 z_{12} z_{13} + x_4 x_6 z_{11} z_{13} + x_5 x_6 z_{11} z_{12}), \\
\beta_{12}^{(2)}(X, Z) &= x_1^2 z_{11} z_{21} + x_2^2 z_{12} z_{22} + x_3^2 z_{13} z_{23} \\
&\quad + \frac{1}{4} \{ (x_4^2 + x_5^2) z_{11} z_{21} + (x_4^2 + x_6^2) z_{12} z_{22} + (x_5^2 + x_6^2) z_{13} z_{23} \} \\
&\quad + \frac{1}{2} \left( x_1 x_4 + x_2 x_4 + \frac{1}{2} x_5 x_6 \right) (z_{11} z_{22} + z_{12} z_{21}) \\
&\quad + \frac{1}{2} \left( x_1 x_5 + x_3 x_5 + \frac{1}{2} x_4 x_6 \right) (z_{11} z_{23} + z_{13} z_{21}) \\
&\quad + \frac{1}{2} \left( x_2 x_6 + x_3 x_6 + \frac{1}{2} x_4 x_5 \right) (z_{12} z_{23} + z_{13} z_{22}), \\
\beta_{22}^{(2)}(X, Z) &= x_1^2 z_{21}^2 + x_2^2 z_{22}^2 + x_3^2 z_{23}^2 \\
&\quad + \frac{1}{4} \{ x_4^2 (z_{21}^2 + z_{22}^2) + x_5^2 (z_{21}^2 + z_{23}^2) + x_6^2 (z_{22}^2 + z_{23}^2) \} \\
&\quad + (x_1 + x_2) x_4 z_{21} z_{22} + (x_1 + x_3) x_5 z_{21} z_{23} + (x_2 + x_3) x_6 z_{22} z_{23} \\
&\quad + \frac{1}{2} (x_4 x_5 z_{22} z_{23} + x_4 x_6 z_{21} z_{23} + x_5 x_6 z_{21} z_{22}).
\end{aligned}$$

Set

$$\Delta_{ab} := \det \begin{pmatrix} \beta_{11}^{(a)} & \beta_{12}^{(b)} \\ \beta_{12}^{(a)} & \beta_{22}^{(b)} \end{pmatrix} \quad \text{for } a, b = 0, 1, 2.$$

By a direct computation, we can show that

$$(6.3) \quad (\alpha_1^2 - \alpha_2) \Delta_{00} - 2 \alpha_1 (\Delta_{01} + \Delta_{10}) + 2 (\Delta_{02} + \Delta_{11} + \Delta_{20}) = 0.$$

We take a coordinate  $(Y, V)$  in  $\mathcal{P}_{3,2}$ , that is,

$$Y = \begin{pmatrix} y_1 & y_4 & y_5 \\ y_4 & y_2 & y_6 \\ y_5 & y_6 & y_3 \end{pmatrix} \quad \text{and} \quad V = \begin{pmatrix} v_{11} & v_{12} & v_{13} \\ v_{21} & v_{22} & v_{23} \end{pmatrix}.$$

Put

$$\frac{\partial}{\partial Y} = \begin{pmatrix} \frac{\partial}{\partial y_1} & \frac{1}{2} \frac{\partial}{\partial y_4} & \frac{1}{2} \frac{\partial}{\partial y_5} \\ \frac{1}{2} \frac{\partial}{\partial y_4} & \frac{\partial}{\partial y_2} & \frac{1}{2} \frac{\partial}{\partial y_6} \\ \frac{1}{2} \frac{\partial}{\partial y_5} & \frac{1}{2} \frac{\partial}{\partial y_6} & \frac{\partial}{\partial y_3} \end{pmatrix} \quad \text{and} \quad \begin{pmatrix} \frac{\partial}{\partial v_{11}} & \frac{\partial}{\partial v_{12}} & \frac{\partial}{\partial v_{13}} \\ \frac{\partial}{\partial v_{21}} & \frac{\partial}{\partial v_{22}} & \frac{\partial}{\partial v_{23}} \end{pmatrix}.$$

Consider the following differential operators

$$D_i := \text{tr} \left( \left( 2Y \frac{\partial}{\partial Y} \right)^i \right), \quad i = 1, 2, 3$$

and

$$\Omega_{pq}^{(k)} = \left\{ \frac{\partial}{\partial V} \left( 2Y \frac{\partial}{\partial Y} \right)^k Y^t \left( \frac{\partial}{\partial V} \right) \right\}_{pq}, \quad k = 0, 1, 2, \quad 1 \leq p \leq q \leq 2.$$

Note that  $D_1, D_2, D_3, \Omega_{11}^{(0)}, \dots, \Omega_{22}^{(2)}$  are  $GL_{3,2}$ -invariant. For brevity, we put

$$\partial_{ij} = \frac{\partial}{\partial v_{ij}}, \quad i = 1, 2, \quad j = 1, 2, 3.$$

It is easily seen that

$$\begin{aligned} D_1 &= \text{tr} \left( 2Y \frac{\partial}{\partial Y} \right) = 2 \sum_{i=1}^6 y_i \frac{\partial}{\partial y_i}, \\ \Omega_{11}^{(0)} &= y_1 \partial_{11}^2 + y_2 \partial_{12}^2 + y_3 \partial_{13}^2 + 2y_4 \partial_{11} \partial_{12} + 2y_5 \partial_{11} \partial_{13} + 2y_6 \partial_{12} \partial_{13}, \\ \Omega_{12}^{(0)} &= y_1 \partial_{11} \partial_{21} + y_2 \partial_{12} \partial_{22} + y_3 \partial_{13} \partial_{23} + y_4 (\partial_{11} \partial_{22} + \partial_{12} \partial_{21}) \\ &\quad + y_5 (\partial_{11} \partial_{23} + \partial_{13} \partial_{21}) + y_6 (\partial_{12} \partial_{23} + \partial_{13} \partial_{22}), \\ \Omega_{22}^{(0)} &= y_1 \partial_{21}^2 + y_2 \partial_{22}^2 + y_3 \partial_{23}^2 + 2y_4 \partial_{21} \partial_{22} + 2y_5 \partial_{21} \partial_{23} + 2y_6 \partial_{22} \partial_{23}. \end{aligned}$$

Then we have the following relations

$$(6.4) \quad [D_i, D_j] = 0 \quad \text{for all } i, j = 1, 2, 3,$$

$$(6.5) \quad [\Omega_{kl}^{(0)}, \Omega_{pq}^{(0)}] = 0, \quad 1 \leq k \leq l \leq 2, \quad 1 \leq p \leq q \leq 2$$

and

$$(6.6) \quad [D_1, \Omega_{11}^{(0)}] = 2\Omega_{11}^{(0)}, \quad [D_1, \Omega_{12}^{(0)}] = 2\Omega_{12}^{(0)}, \quad [D_1, \Omega_{22}^{(0)}] = 2\Omega_{22}^{(0)}.$$

Therefore,  $\mathbb{D}(\mathcal{P}_{3,2})$  is not commutative.

## 7. The case when $n = 4$

### 6.1. The case when $n = 4$ and $m = 1$

In this case,

$$GL_{4,1} = GL(4, \mathbb{R}) \times \mathbb{R}^{(1,4)}, \quad K = O(4) \quad \text{and} \quad GL_{4,1}/K = \mathcal{P}_4 \times \mathbb{R}^{(1,4)} = \mathcal{P}_{4,1}.$$

We see easily that

$$\mathfrak{p}_* = \left\{ (X, Z) \mid X = {}^t X \in \mathbb{R}^{(4,4)}, Z \in \mathbb{R}^{(1,4)} \right\}.$$

Put

$$\begin{aligned} E_1 &= \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, E_2 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, E_3 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \\ E_4 &= \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}, E_5 = \begin{pmatrix} 0 & \frac{1}{2} & 0 & 0 \\ \frac{1}{2} & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, E_6 = \begin{pmatrix} 0 & 0 & \frac{1}{2} & 0 \\ 0 & 0 & 0 & 0 \\ \frac{1}{2} & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \\ E_7 &= \begin{pmatrix} 0 & 0 & 0 & \frac{1}{2} \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ \frac{1}{2} & 0 & 0 & 0 \end{pmatrix}, E_8 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & \frac{1}{2} & 0 \\ 0 & \frac{1}{2} & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \\ E_9 &= \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{2} \\ 0 & 0 & 0 & 0 \\ 0 & \frac{1}{2} & 0 & 0 \end{pmatrix}, E_{10} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{2} \\ 0 & 0 & \frac{1}{2} & 0 \end{pmatrix}. \end{aligned}$$

Let  $O_4$  be the  $4 \times 4$  zero matrix and let  $O_{1,4} = (0, 0, 0, 0) \in \mathbb{R}^{(1,4)}$ . Put

$$\begin{aligned} e_i &= (E_i, O_{1,4}), \quad 1 \leq i \leq 10, \\ f_1 &= (O_4, (1, 0, 0, 0)), \quad f_2 = (O_4, (0, 1, 0, 0)), \\ f_3 &= (O_4, (0, 0, 1, 0)), \quad f_4 = (O_4, (0, 0, 0, 1)). \end{aligned}$$

Then  $\{e_i, f_j \mid 1 \leq i \leq 10, 1 \leq j \leq 4\}$  forms a basis for  $\mathfrak{p}_*$ . Using this basis, we write for variables  $(X, Z) \in \mathfrak{p}_*$ ,

$$X = \begin{pmatrix} x_1 & \frac{1}{2}x_5 & \frac{1}{2}x_6 & \frac{1}{2}x_7 \\ \frac{1}{2}x_5 & x_2 & \frac{1}{2}x_8 & \frac{1}{2}x_9 \\ \frac{1}{2}x_6 & \frac{1}{2}x_8 & x_3 & \frac{1}{2}x_{10} \\ \frac{1}{2}x_7 & \frac{1}{2}x_9 & \frac{1}{2}x_{10} & x_4 \end{pmatrix} \quad \text{and} \quad Z = (z_1, z_2, z_3, z_4).$$

Put

$$(7.1) \quad A = x_1^2 + \frac{1}{4}x_5^2 + \frac{1}{4}x_6 + \frac{1}{4}x_7^2,$$

$$(7.2) \quad B = x_2^2 + \frac{1}{4}x_5^2 + \frac{1}{4}x_8 + \frac{1}{4}x_9^2,$$

$$(7.3) \quad C = x_3^2 + \frac{1}{4}x_6^2 + \frac{1}{4}x_8 + \frac{1}{4}x_{10}^2,$$

$$(7.4) \quad D = x_4^2 + \frac{1}{4}x_7^2 + \frac{1}{4}x_9 + \frac{1}{4}x_{10}^2,$$



$$(7.5) \quad E = \frac{1}{2}(x_1 + x_2)x_5 + \frac{1}{4}(x_6x_8 + x_7x_9),$$

$$(7.6) \quad F = \frac{1}{2}(x_1 + x_3)x_6 + \frac{1}{4}(x_3x_6 + x_5x_8),$$

$$(7.7) \quad G = \frac{1}{2}(x_1 + x_4)x_7 + \frac{1}{4}(x_5x_9 + x_6x_{10}),$$

$$(7.8) \quad H = \frac{1}{2}(x_2 + x_3)x_8 + \frac{1}{4}(x_5x_6 + x_9x_{10}),$$

$$(7.9) \quad I = \frac{1}{2}(x_2 + x_4)x_9 + \frac{1}{4}(x_5x_7 + x_8x_{10}),$$

$$(7.10) \quad J = \frac{1}{2}(x_3 + x_4)x_{10} + \frac{1}{4}(x_6x_{10} + x_6x_7).$$

From Theorem 3.3, the algebra  $\text{Pol}(\mathfrak{p}_*)^K$  is generated by the following polynomials

$$\alpha_1(X, Z) = x_1 + x_2 + x_3 + x_4,$$

$$\alpha_2(X, Z) = x_1^2 + x_2^2 + x_3^2 + x_4^2 + \frac{1}{2}(x_5^2 + x_6^2 + x_7^2 + x_8^2 + x_9^2 + x_{10}^2),$$

$$\begin{aligned} \alpha_3(X, Z) = & x_1^3 + x_2^3 + x_3^3 + x_4^3 \\ & + \frac{3}{4}x_1(x_5^2 + x_6^2 + x_7^2) + \frac{3}{4}x_2(x_5^2 + x_8^2 + x_9^2) \\ & + \frac{3}{4}x_3(x_6^2 + x_8^2 + x_{10}^2) + \frac{3}{4}x_4(x_7^2 + x_9^2 + x_{10}^2) \\ & + \frac{3}{4}(x_5x_6x_8 + x_5x_7x_9 + x_6x_7x_{10} + x_8x_9x_{10}), \end{aligned}$$

$$\alpha_4(X, Z) = A^2 + B^2 + C^2 + D^2 + 2(E^2 + F^2 + G^2 + H^2 + I^2 + J^2),$$

$$\beta_0(X, Z) = z_1^2 + z_2^2 + z_3^2 + z_4^2,$$

$$\begin{aligned} \beta_1(X, Z) = & x_1z_1^2 + x_2z_2^2 + x_3z_3^2 + x_4z_4^2 \\ & + x_5z_1z_2 + x_6z_1z_3 + x_7z_1z_4 + x_8z_2z_3 + x_9z_2z_4 + x_{10}z_3z_4, \end{aligned}$$

$$\begin{aligned} \beta_2(X, Z) = & Az_1^2 + Bz_2^2 + Cz_3^2 + Dz_4^2 \\ & + 2(Ez_1z_2 + Fz_1z_3 + Gz_1z_4 + Hz_2z_3 + Iz_2z_4 + Jz_3z_4), \end{aligned}$$

$$\begin{aligned} \beta_3(X, Z) = & \frac{1}{2}(2Ax_1 + Ex_5 + Fx_6 + Gx_7)z_1^2 \\ & + \frac{1}{2}(2Bx_2 + Ex_5 + Hx_8 + Ix_9)z_2^2 \\ & + \frac{1}{2}(2Cx_3 + Fx_6 + Hx_8 + Jx_{10})z_3^2 \\ & + \frac{1}{2}(2Dx_4 + Gx_7 + Ix_9 + Jx_{10})z_4^2 \\ & + \frac{1}{2}\{2E(x_1 + x_2) + (A + B)x_5 + Hx_6 + Ix_7 + Fx_8 + Gx_9\}z_1z_2 \end{aligned}$$

$$\begin{aligned}
& + \frac{1}{2} \{2F(x_1 + x_3) + Hx_5 + (A + C)x_6 + Jx_7 + Ex_8 + Gx_{10}\} z_1 z_3 \\
& + \frac{1}{2} \{2G(x_1 + x_4) + Ix_5 + Jx_6 + (A + D)x_7 + Ex_9 + Fx_{10}\} z_1 z_4 \\
& + \frac{1}{2} \{2H(x_2 + x_3) + Fx_5 + Ex_6 + (B + C)x_8 + Jx_9 + Ix_{10}\} z_2 z_3 \\
& + \frac{1}{2} \{2I(x_2 + x_4) + Gx_5 + Ex_7 + Jx_8 + (B + D)x_9 + Hx_{10}\} z_2 z_4 \\
& + \frac{1}{2} \{2J(x_3 + x_4) + Gx_6 + Fx_7 + Ix_8 + Hx_9 + (C + D)x_{10}\} z_3 z_4.
\end{aligned}$$

We take a coordinate  $(Y, V)$  in  $\mathcal{P}_{4,1}$ , that is,

$$Y = \begin{pmatrix} y_1 & y_5 & y_6 & y_7 \\ y_5 & y_2 & y_8 & y_9 \\ y_6 & y_8 & y_3 & y_{10} \\ y_7 & y_9 & y_{10} & y_4 \end{pmatrix} \quad \text{and} \quad V = (v_1, v_2, v_3, v_4).$$

Put

$$\frac{\partial}{\partial Y} = \begin{pmatrix} \frac{\partial}{\partial y_1} & \frac{1}{2} \frac{\partial}{\partial y_5} & \frac{1}{2} \frac{\partial}{\partial y_6} & \frac{1}{2} \frac{\partial}{\partial y_7} \\ \frac{1}{2} \frac{\partial}{\partial y_5} & \frac{\partial}{\partial y_2} & \frac{1}{2} \frac{\partial}{\partial y_8} & \frac{1}{2} \frac{\partial}{\partial y_9} \\ \frac{1}{2} \frac{\partial}{\partial y_6} & \frac{1}{2} \frac{\partial}{\partial y_8} & \frac{\partial}{\partial y_3} & \frac{1}{2} \frac{\partial}{\partial y_{10}} \\ \frac{1}{2} \frac{\partial}{\partial y_7} & \frac{1}{2} \frac{\partial}{\partial y_9} & \frac{1}{2} \frac{\partial}{\partial y_{10}} & \frac{\partial}{\partial y_4} \end{pmatrix} \quad \text{and} \quad \frac{\partial}{\partial V} = \left( \frac{\partial}{\partial v_1}, \frac{\partial}{\partial v_2}, \frac{\partial}{\partial v_3}, \frac{\partial}{\partial v_4} \right).$$

Let

$$D_i = \text{tr} \left( \left( 2Y \frac{\partial}{\partial Y} \right)^i \right), \quad i = 1, 2, 3, 4$$

and

$$\Omega_j = \frac{\partial}{\partial V} \left( 2Y \frac{\partial}{\partial Y} \right)^j Y^t \left( \frac{\partial}{\partial V} \right), \quad j = 0, 1, 2, 3.$$

It is easily seen that

$$D_1 = \text{tr} \left( 2Y \frac{\partial}{\partial Y} \right) = 2 \sum_{i=1}^{10} y_i \frac{\partial}{\partial y_i}.$$

For brevity, we put

$$\partial_i = \frac{\partial}{\partial v_i}, \quad i = 1, 2, 3, 4.$$

Then we get

$$\begin{aligned}
\Omega_0 & = y_1 \partial_1^2 + y_2 \partial_2^2 + y_3 \partial_3^2 + y_4 \partial_4^2 + 2y_5 \partial_1 \partial_2 \\
& \quad + 2y_6 \partial_1 \partial_3 + 2y_7 \partial_1 \partial_4 + 2y_8 \partial_2 \partial_3 + 2y_9 \partial_2 \partial_4 + 2y_{10} \partial_3 \partial_4.
\end{aligned}$$

We observe that  $D_1, D_2, D_3, D_4, \Omega_0, \Omega_1, \Omega_2, \Omega_3$  are invariant differential operators in  $\mathbb{D}(\mathcal{P}_{4,1})$ . Then we have the following relations

$$(7.11) \quad [D_i, D_j] = 0 \quad \text{for all } i, j = 1, 2, 3, 4$$

and

$$(7.12) \quad [D_1, \Omega_0] = 2\Omega_0.$$

Therefore,  $\mathbb{D}(\mathcal{P}_{4,1})$  is not commutative.

## 6.2. The case when $n = 4$ and $m = 2$

In this case,

$$GL_{4,2} = GL(4, \mathbb{R}) \times \mathbb{R}^{(2,4)}, \quad K = O(4) \quad \text{and} \quad \mathcal{P}_{4,2} = GL_{4,2}/K = \mathcal{P}_4 \times \mathbb{R}^{(2,4)}.$$

We see easily that

$$\mathfrak{p}_* = \left\{ (X, Z) \mid X = {}^t X \in \mathbb{R}^{(4,4)}, \quad Z \in \mathbb{R}^{(2,4)} \right\}.$$

Put

$$\begin{aligned} E_1 &= \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \quad E_2 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \quad E_3 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \\ E_4 &= \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}, \quad E_5 = \begin{pmatrix} 0 & \frac{1}{2} & 0 & 0 \\ \frac{1}{2} & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \quad E_6 = \begin{pmatrix} 0 & 0 & \frac{1}{2} & 0 \\ 0 & 0 & 0 & 0 \\ \frac{1}{2} & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \\ E_7 &= \begin{pmatrix} 0 & 0 & 0 & \frac{1}{2} \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ \frac{1}{2} & 0 & 0 & 0 \end{pmatrix}, \quad E_8 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & \frac{1}{2} & 0 \\ 0 & \frac{1}{2} & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \\ E_9 &= \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{2} \\ 0 & 0 & 0 & 0 \\ 0 & \frac{1}{2} & 0 & 0 \end{pmatrix}, \quad E_{10} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{2} \\ 0 & 0 & \frac{1}{2} & 0 \end{pmatrix}. \end{aligned}$$

Let  $O_4$  be the  $4 \times 4$  zero matrix and let

$$O_{2,4} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \in \mathbb{R}^{(2,4)}.$$

Put

$$\begin{aligned} e_i &= (E_i, O_{2,4}), \quad 1 \leq i \leq 10, \\ f_1 &= \left( O_4, \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \right), \quad f_2 = \left( O_4, \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \right), \\ f_3 &= \left( O_4, \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \right), \quad f_4 = \left( O_4, \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix} \right), \\ f_5 &= \left( O_4, \begin{pmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \right), \quad f_6 = \left( O_4, \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix} \right), \end{aligned}$$

$$f_7 = \left( O_4, \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{pmatrix} \right), \quad f_8 = \left( O_4, \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \right).$$

Then  $\{e_i, f_j \mid 1 \leq i \leq 10, 1 \leq j \leq 8\}$  forms a basis for  $\mathfrak{p}_*$ . Using this basis, we write for variables  $(X, Z) \in \mathfrak{p}_*$ ,

$$X = \begin{pmatrix} x_1 & \frac{1}{2}x_5 & \frac{1}{2}x_6 & \frac{1}{2}x_7 \\ \frac{1}{2}x_5 & x_2 & \frac{1}{2}x_8 & \frac{1}{2}x_9 \\ \frac{1}{2}x_6 & \frac{1}{2}x_8 & x_3 & \frac{1}{2}x_{10} \\ \frac{1}{2}x_7 & \frac{1}{2}x_9 & \frac{1}{2}x_{10} & x_4 \end{pmatrix} \quad \text{and} \quad Z = \begin{pmatrix} z_{11} & z_{12} & z_{13} & z_{14} \\ z_{21} & z_{22} & z_{23} & z_{24} \end{pmatrix}.$$

Set

$$\begin{aligned} \square_{11} &= \frac{1}{2} (2A x_1 + E x_5 + F x_6 + G x_7), \\ \square_{22} &= \frac{1}{2} (2B x_2 + E x_5 + H x_8 + I x_9), \\ \square_{33} &= \frac{1}{2} (2C x_3 + F x_6 + H x_8 + J x_{10}), \\ \square_{44} &= \frac{1}{2} (2D x_4 + G x_7 + I x_9 + J x_{10}), \\ \square_{12} &= \frac{1}{2} \{2E(x_1 + x_2) + (A + B)x_5 + Hx_6 + Ix_7 + Fx_8 + Gx_9\}, \\ \square_{13} &= \frac{1}{2} \{2F(x_1 + x_3) + Hx_5 + (A + C)x_6 + Jx_7 + Ex_8 + Gx_{10}\}, \\ \square_{14} &= \frac{1}{2} \{2G(x_1 + x_4) + Ix_5 + Jx_6 + (A + D)x_7 + Ex_9 + Fx_{10}\}, \\ \square_{23} &= \frac{1}{2} \{2H(x_2 + x_3) + Fx_5 + Ex_6 + (B + C)x_8 + Jx_9 + Ix_{10}\}, \\ \square_{24} &= \frac{1}{2} \{2I(x_2 + x_4) + Gx_5 + Ex_7 + Jx_8 + (B + D)x_9 + Hx_{10}\}, \\ \square_{34} &= \frac{1}{2} \{2J(x_3 + x_4) + Gx_6 + Fx_7 + Ix_8 + Hx_9 + (C + D)x_{10}\}. \end{aligned}$$

From Theorem 3.3, the algebra  $\text{Pol}(\mathfrak{p}_*)^K$  is generated by the following 16 polynomials

$$\begin{aligned} \alpha_1(X, Z) &= x_1 + x_2 + x_3 + x_4, \\ \alpha_2(X, Z) &= x_1^2 + x_2^2 + x_3^2 + x_4^2 + \frac{1}{2} (x_5^2 + x_6^2 + x_7^2 + x_8^2 + x_9^2 + x_{10}^2), \\ \alpha_3(X, Z) &= x_1^3 + x_2^3 + x_3^3 + x_4^3 \\ &\quad + \frac{3}{4} x_1 (x_5^2 + x_6^2 + x_7^2) + \frac{3}{4} x_2 (x_5^2 + x_8^2 + x_9^2) \\ &\quad + \frac{3}{4} x_3 (x_6^2 + x_8^2 + x_{10}^2) + \frac{3}{4} x_4 (x_7^2 + x_9^2 + x_{10}^2) \\ &\quad + \frac{3}{4} (x_5 x_6 x_8 + x_5 x_7 x_9 + x_6 x_7 x_{10} + x_8 x_9 x_{10}), \end{aligned}$$

$$\begin{aligned}
\alpha_4(X, Z) &= A^2 + B^2 + C^2 + D^2 + 2(E^2 + F^2 + G^2 + H^2 + I^2 + J^2), \\
\beta_{11}^{(0)}(X, Z) &= z_{11}^2 + z_{12}^2 + z_{13}^2 + z_{14}^2, \\
\beta_{12}^{(0)}(X, Z) &= z_{11}z_{21} + z_{12}z_{22} + z_{13}z_{23} + z_{14}z_{24}, \\
\beta_{22}^{(0)}(X, Z) &= z_{21}^2 + z_{22}^2 + z_{23}^2 + z_{24}^2, \\
\beta_{11}^{(1)}(X, Z) &= x_1z_{11}^2 + x_2z_{12}^2 + x_3z_{13}^2 + x_4z_{14}^2 + x_5z_{11}z_{12} \\
&\quad + x_6z_{11}z_{13} + x_7z_{11}z_{14} + x_8z_{12}z_{13} + x_9z_{12}z_{14} + x_{10}z_{13}z_{14}, \\
\beta_{12}^{(1)}(X, Z) &= x_1z_{11}z_{21} + x_2z_{12}z_{22} + x_3z_{13}z_{23} + x_4z_{14}z_{24} \\
&\quad + \frac{1}{2}x_5(z_{11}z_{22} + z_{12}z_{21}) + \frac{1}{2}x_6(z_{11}z_{23} + z_{13}z_{21}) \\
&\quad + \frac{1}{2}x_7(z_{11}z_{24} + z_{14}z_{21}) + \frac{1}{2}x_8(z_{12}z_{23} + z_{13}z_{22}) \\
&\quad + \frac{1}{2}x_9(z_{12}z_{24} + z_{14}z_{22}) + \frac{1}{2}x_{10}(z_{13}z_{24} + z_{14}z_{23}), \\
\beta_{22}^{(1)}(X, Z) &= x_1z_{21}^2 + x_2z_{22}^2 + x_3z_{23}^2 + x_4z_{24}^2 + x_5z_{21}z_{22} \\
&\quad + x_6z_{21}z_{23} + x_7z_{21}z_{24} + x_8z_{22}z_{23} + x_9z_{22}z_{24} + x_{10}z_{23}z_{24}, \\
\beta_{11}^{(2)}(X, Z) &= Az_{11}^2 + Bz_{12}^2 + Cz_{13}^2 + Dz_{14}^2 + 2Ez_{11}z_{12} + 2Fz_{11}z_{13} \\
&\quad + 2Gz_{11}z_{14} + 2Hz_{12}z_{13} + 2Iz_{12}z_{14} + 2Jz_{13}z_{14}, \\
\beta_{12}^{(2)}(X, Z) &= Az_{11}z_{21} + Bz_{12}z_{22} + Cz_{13}z_{23} + Dz_{14}z_{24} \\
&\quad + E(z_{11}z_{22} + z_{12}z_{21}) + F(z_{11}z_{23} + z_{13}z_{21}) \\
&\quad + G(z_{11}z_{24} + z_{14}z_{21}) + H(z_{12}z_{23} + z_{13}z_{22}) \\
&\quad + I(z_{12}z_{24} + z_{14}z_{22}) + J(z_{13}z_{24} + z_{14}z_{23}), \\
\beta_{22}^{(2)}(X, Z) &= Az_{21}^2 + Bz_{22}^2 + Cz_{23}^2 + Dz_{24}^2 + 2Ez_{21}z_{22} + 2Fz_{21}z_{23} \\
&\quad + 2Gz_{21}z_{24} + 2Hz_{22}z_{23} + 2Iz_{22}z_{24} + 2Jz_{23}z_{24}, \\
\beta_{11}^{(3)}(X, Z) &= \square_{11}z_{11}^2 + \square_{22}z_{12}^2 + \square_{33}z_{13}^2 + \square_{44}z_{14}^2 + \square_{12}z_{11}z_{12} \\
&\quad + \square_{13}z_{11}z_{13} + \square_{14}z_{11}z_{14} + \square_{23}z_{12}z_{13} \\
&\quad + \square_{24}z_{12}z_{14} + \square_{34}z_{13}z_{14}, \\
\beta_{12}^{(3)}(X, Z) &= \square_{11}z_{11}z_{21} + \square_{22}z_{12}z_{22} + \square_{33}z_{13}z_{23} + \square_{44}z_{14}z_{24} \\
&\quad + \square_{12}z_{11}z_{22} + \square_{13}z_{11}z_{23} + \square_{14}z_{11}z_{24} + \square_{23}z_{12}z_{23} \\
&\quad + \square_{24}z_{12}z_{24} + \square_{34}z_{13}z_{24}, \\
\beta_{22}^{(3)}(X, Z) &= \square_{11}z_{21}^2 + \square_{22}z_{22}^2 + \square_{33}z_{23}^2 + \square_{44}z_{24}^2 + \square_{12}z_{21}z_{22} \\
&\quad + \square_{13}z_{21}z_{23} + \square_{14}z_{21}z_{24} + \square_{23}z_{22}z_{23} \\
&\quad + \square_{24}z_{22}z_{24} + \square_{34}z_{23}z_{24}.
\end{aligned}$$

Here,  $A, B, C, \dots, J$  are defined as in (7.1)-(7.10).

Set

$$\Delta_{ab} := \det \begin{pmatrix} \beta_{11}^{(a)} & \beta_{12}^{(b)} \\ \beta_{12}^{(a)} & \beta_{22}^{(b)} \end{pmatrix} \quad \text{for } a, b = 0, 1, 2, 3.$$

By a tedious direct computation, we can show that

$$(7.13) \quad (\alpha_1^3 - 3\alpha_1\alpha_2 + 2\alpha_3)\Delta_{00} - 3(\alpha_1^2 - \alpha_2)(\Delta_{01} + \Delta_{10}) \\ + 6\alpha_1(\Delta_{02} + \Delta_{11} + \Delta_{20}) + 6(\Delta_{03} + \Delta_{12} + \Delta_{21} + \Delta_{30}) = 0.$$

Take a coordinate  $(Y, V)$  in  $\mathcal{P}_{4,2}$ , that is,

$$Y = \begin{pmatrix} y_1 & y_5 & y_6 & y_7 \\ y_5 & y_2 & y_8 & y_9 \\ y_6 & y_8 & y_3 & y_{10} \\ y_7 & y_9 & y_{10} & y_4 \end{pmatrix} \quad \text{and} \quad V = \begin{pmatrix} v_{11} & v_{12} & v_{13} & v_{14} \\ v_{21} & v_{22} & v_{23} & v_{24} \end{pmatrix}.$$

Put

$$\frac{\partial}{\partial Y} = \begin{pmatrix} \frac{\partial}{\partial y_1} & \frac{1}{2} \frac{\partial}{\partial y_5} & \frac{1}{2} \frac{\partial}{\partial y_6} & \frac{1}{2} \frac{\partial}{\partial y_7} \\ \frac{1}{2} \frac{\partial}{\partial y_5} & \frac{\partial}{\partial y_2} & \frac{1}{2} \frac{\partial}{\partial y_8} & \frac{1}{2} \frac{\partial}{\partial y_9} \\ \frac{1}{2} \frac{\partial}{\partial y_6} & \frac{1}{2} \frac{\partial}{\partial y_8} & \frac{\partial}{\partial y_3} & \frac{1}{2} \frac{\partial}{\partial y_{10}} \\ \frac{1}{2} \frac{\partial}{\partial y_7} & \frac{1}{2} \frac{\partial}{\partial y_9} & \frac{1}{2} \frac{\partial}{\partial y_{10}} & \frac{\partial}{\partial y_4} \end{pmatrix} \quad \text{and} \quad \frac{\partial}{\partial V} = \begin{pmatrix} \frac{\partial}{\partial v_{11}} & \frac{\partial}{\partial v_{12}} & \frac{\partial}{\partial v_{13}} & \frac{\partial}{\partial v_{14}} \\ \frac{\partial}{\partial v_{21}} & \frac{\partial}{\partial v_{22}} & \frac{\partial}{\partial v_{23}} & \frac{\partial}{\partial v_{24}} \end{pmatrix}.$$

Let

$$D_i = \text{tr} \left( \left( 2Y \frac{\partial}{\partial Y} \right)^i \right), \quad i = 1, 2, 3, 4$$

and

$$\Omega_{pq}^{(k)} = \left\{ \frac{\partial}{\partial V} \left( 2Y \frac{\partial}{\partial Y} \right)^k Y^t \left( \frac{\partial}{\partial V} \right) \right\}_{pq}, \quad k = 0, 1, 2, 3, \quad 1 \leq p \leq q \leq 2.$$

Note that  $D_1, D_2, D_3, D_4, \Omega_{11}^{(0)}, \dots, \Omega_{22}^{(3)}$  are  $GL_{4,2}$ -invariant. It is easily seen that

$$D_1 = \text{tr} \left( 2Y \frac{\partial}{\partial Y} \right) = 2 \sum_{i=1}^{10} y_i \frac{\partial}{\partial y_i}.$$

For brevity, we put

$$\partial_{ij} = \frac{\partial}{\partial v_{ij}}, \quad i = 1, 2, \quad 1 \leq j \leq 4.$$

Then we get

$$\Omega_{11}^{(0)} = y_1 \partial_{11}^2 + y_2 \partial_{12}^2 + y_3 \partial_{13}^2 + y_4 \partial_{14}^2 + 2y_5 \partial_{11} \partial_{12} + 2y_6 \partial_{11} \partial_{13} \\ + 2y_7 \partial_{11} \partial_{14} + 2y_8 \partial_{12} \partial_{13} + 2y_9 \partial_{12} \partial_{14} + 2y_{10} \partial_{13} \partial_{14},$$

$$\Omega_{12}^{(0)} = y_1 \partial_{11} \partial_{21} + y_2 \partial_{12} \partial_{22} + y_3 \partial_{13} \partial_{23} + y_4 \partial_{14} \partial_{24} \\ + y_5 (\partial_{11} \partial_{22} + \partial_{12} \partial_{21}) + y_6 (\partial_{11} \partial_{23} + \partial_{13} \partial_{21}) \\ + y_7 (\partial_{11} \partial_{24} + \partial_{14} \partial_{21}) + y_8 (\partial_{12} \partial_{23} + \partial_{13} \partial_{22})$$

$$\begin{aligned}
& + y_9 (\partial_{12}\partial_{24} + \partial_{14}\partial_{22}) + y_{10} (\partial_{13}\partial_{24} + \partial_{14}\partial_{23}), \\
\Omega_{22}^{(0)} & = y_1 \partial_{21}^2 + y_2 \partial_{22}^2 + y_3 \partial_{23}^2 + y_4 \partial_{24}^2 + 2 y_5 \partial_{21}\partial_{22} + 2 y_6 \partial_{21}\partial_{23} \\
& + 2 y_7 \partial_{21}\partial_{24} + 2 y_8 \partial_{22}\partial_{23} + 2 y_9 \partial_{22}\partial_{24} + 2 y_{10} \partial_{23}\partial_{24}.
\end{aligned}$$

Then we have the following relations

$$(7.14) \quad [D_i, D_j] = 0 \quad \text{for all } i, j = 1, 2, 3, 4,$$

$$(7.15) \quad [\Omega_{kl}^{(0)}, \Omega_{pq}^{(0)}] = 0, \quad 1 \leq k \leq l \leq 2, \quad 1 \leq p \leq q \leq 2,$$

and

$$(7.16) \quad [D_1, \Omega_{11}^{(0)}] = 2 \Omega_{11}^{(0)}, \quad [D_1, \Omega_{12}^{(0)}] = 2 \Omega_{12}^{(0)}, \quad [D_1, \Omega_{22}^{(0)}] = 2 \Omega_{22}^{(0)}.$$

Therefore,  $\mathbb{D}(\mathcal{P}_{4,2})$  is not commutative.

### 8. Final remarks

In this section, we present some open problems and discuss a notion of automorphic forms on  $\mathcal{P}_{n,m}$  using  $GL_{n,m}$ -invariant differential operators on the Minkowski-Euclid space  $\mathcal{P}_{n,m}$ .

Recall the invariant polynomials  $\alpha_j$  ( $1 \leq j \leq n$ ) from (3.11) and  $\beta_{pq}^{(k)}$  ( $0 \leq k \leq n-1$ ,  $1 \leq p \leq q \leq m$ ) from (3.12). Also recall the invariant differential operators  $D_j$  ( $1 \leq j \leq n$ ) from (3.19) and  $\Omega_{pq}^{(k)}$  ( $0 \leq k \leq n-1$ ,  $1 \leq p \leq q \leq m$ ) from (3.20).

**Theorem 8.1.** *The following relations hold:*

$$(8.1) \quad [D_i, D_j] = 0 \quad \text{for all } 1 \leq i, j \leq n,$$

$$(8.2) \quad [\Omega_{kl}^{(0)}, \Omega_{pq}^{(0)}] = 0, \quad 1 \leq k \leq l \leq m, \quad 1 \leq p \leq q \leq m,$$

and

$$(8.3) \quad [D_1, \Omega_{pq}^{(0)}] = 2 \Omega_{pq}^{(0)} \quad \text{for all } 1 \leq p \leq q \leq m.$$

*Proof.* The relation (8.1) follows from the work of Atle Selberg (cf. [8, 10, 11]). Take a coordinate  $(Y, V)$  in  $\mathcal{P}_{n,m}$  with  $Y = (y_{ij})$  and  $V = (v_{kl})$ . Put

$$\frac{\partial}{\partial Y} = \left( \frac{1 + \delta_{ij}}{2} \frac{\partial}{\partial y_{ij}} \right) \quad \text{and} \quad \frac{\partial}{\partial V} = \left( \frac{\partial}{\partial v_{kl}} \right),$$

where  $1 \leq i, j, l \leq n$  and  $1 \leq k \leq m$ . Then we get

$$\begin{aligned}
D_1 & = 2 \sum_{1 \leq i \leq j \leq n} y_{ij} \frac{\partial}{\partial y_{ij}}, \\
\Omega_{pq}^{(0)} & = \sum_{a=1}^n y_{aa} \frac{\partial^2}{\partial v_{pa} \partial v_{qa}} + \sum_{1 \leq a < b \leq n} y_{ab} \left( \frac{\partial^2}{\partial v_{pa} \partial v_{qb}} + \frac{\partial^2}{\partial v_{pb} \partial v_{qa}} \right).
\end{aligned}$$

By a direct calculation, we obtain the desired relations (8.2) and (8.3).  $\square$

**Conjecture 2.**

$$(8.4) \quad \Theta_{n,m}(\alpha_j) = D_j \quad \text{for all } 1 \leq j \leq n,$$

$$(8.5) \quad \Theta_{n,m}(\beta_{pq}^{(k)}) = \Omega_{pq}^{(k)} \quad \text{for all } 0 \leq k \leq n-1, 1 \leq p \leq q \leq m.$$

We refer to Conjecture 1 in Section 2.

**Conjecture 3.** The invariants  $D_j$  ( $1 \leq j \leq n$ ) and  $\Omega_{pq}^{(k)}$  ( $0 \leq k \leq n-1, 1 \leq p \leq q \leq m$ ) generate the noncommutative algebra  $\mathbb{D}(\mathcal{P}_{n,m})$ .

**Conjecture 4.** The above relations (8.1), (8.2) and (8.3) generate all relations among the set

$$\left\{ D_j, \Omega_{pq}^{(k)} \mid 1 \leq j \leq n, 0 \leq k \leq n-1, 1 \leq p \leq q \leq m \right\}.$$

**Problem 8.** Find a natural way to construct generators of  $\mathbb{D}(\mathcal{P}_{n,m})$ .

Using  $GL_{n,m}$ -invariant differential operators on the Minkowski-Euclid space  $\mathcal{P}_{n,m}$ , we introduce a notion of automorphic forms on  $\mathcal{P}_{n,m}$  (cf. [11]).

Let

$$\Gamma_{n,m} := GL(n, \mathbb{Z}) \times \mathbb{Z}^{(m,n)}$$

be the arithmetic subgroup of  $GL_{n,m}$ . Let  $\mathcal{Z}_{n,m}$  be the center of  $\mathbb{D}(\mathcal{P}_{n,m})$ .

**Definition 8.1.** A smooth function  $f : \mathcal{P}_{n,m} \rightarrow \mathbb{C}$  is said to be an automorphic form for  $\Gamma_{n,m}$  if it satisfies the following conditions:

- (A1)  $f$  is  $\Gamma_{n,m}$ -invariant.
- (A2)  $f$  is an eigenfunction of any differential operator in the center  $\mathcal{Z}_{n,m}$  of  $\mathbb{D}(\mathcal{P}_{n,m})$ .
- (A3)  $f$  has a growth condition.

We define another notion of automorphic forms as follows.

**Definition 8.2.** Let  $\mathbb{D}_\spadesuit$  be a commutative subalgebra of  $\mathbb{D}(\mathcal{P}_{n,m})$  containing the Laplacian  $\Delta_{n,m;A,B}$ . A smooth function  $f : \mathcal{P}_{n,m} \rightarrow \mathbb{C}$  is said to be an automorphic form for  $\Gamma_{n,m}$  with respect to  $\mathbb{D}_\spadesuit$  if it satisfies the following conditions:

- (A1)  $f$  is  $\Gamma_{n,m}$ -invariant.
- (A2)  $f$  is an eigenfunction of any differential operator in  $\mathbb{D}_\spadesuit$ .
- (A3)  $f$  has a growth condition.

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